# Zolotarev $\omega$-Polynomials in $W^{r} H^{\omega}[0,1]$ 

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The main result of this paper characterizes generalizations of Zolotarev polynomials as extremal functions in the Kolmogorov-Landau problem

$$
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\omega}[0,1],\|f\|_{\mathrm{C}[0,1]} \leqslant B,
$$

where $\omega(t)$ is a concave modulus of continuity, $r, m: 1 \leqslant m \leqslant r$, are integers, and $B \geqslant B_{0}(r, m, \omega)$.

We show that the extremal functions $Z_{B}$ have $r+1$ points of alternance and the full modulus of continuity of $Z_{B}^{(r)}: \omega\left(Z_{B}^{(r)} ; t\right)=\omega(t)$ for all $t \in[0,1]$. This generalizes the Karlin's result on the extremality of classical Zolotarev polynomials in the problem ( $\star$ ) for $\omega(t)=t$ and all $B \geqslant B_{r}$. © 1997 Academic Press

## 0. INTRODUCTION

### 0.1. Classical Zolotarev Polynomials

The family $\left\{Z_{B}\right\}_{B>0}$ of classical Zolotarev polynomials of degree $r+1$ on the interval $[0,1]$ can be characterized as follows:
for any $B>0$, there exist points $\left\{\tau_{i}(B)\right\}_{i=0}^{r}, 0=: \tau_{0}(B)<\cdots<\tau_{r}(B) \leqslant 1$ and such a polynomial $Z_{B}(x)=x^{r+1} /(r+1)!+\sum_{i=0}^{r} a_{i} x^{i}$ that

$$
\begin{equation*}
Z_{B}\left(\tau_{i}(B)\right)=(-1)^{r+1+i}\left\|Z_{B}\right\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]}=(-1)^{r+1+i} B, \quad i=0, \ldots, r . \tag{0.1}
\end{equation*}
$$

Let $C_{r}(x)$ be the Chebyshev polynomial of degree $r+1$ with the leading coefficient $1 /(r+1)$ !:

$$
\begin{equation*}
C_{r}(x)=\frac{2^{-2 r-1}}{(r+1)!} \cos [(r+1) \arccos (2 x-1)], \quad x \in[0,1] . \tag{0.2}
\end{equation*}
$$

Let $L_{r}:=\left\|C_{r}\right\|_{\mathbb{C}[0,1]}=2^{-2 r-1} /(r+1)!$ By $(0.2)$,

$$
\begin{equation*}
\left\{T_{i}=\frac{1}{2}(1+\cos (\pi i /(r+1)))\right\}_{i=0}^{r+1} \tag{340}
\end{equation*}
$$

is the collection of alternance points of $C_{r}(x)$ on the interval $[0,1]$ :

$$
\begin{equation*}
C_{r}\left(T_{i}\right)=(-1)^{r+1+i}\left\|C_{r}\right\|_{\mathbb{C}[0,1]}=(-1)^{r+1+i} L_{r}, \quad i=0, \ldots, r+1 . \tag{0.3}
\end{equation*}
$$

Let $K_{r}:=L_{r} \cdot T_{r}^{-(r+1)}$. For $0<B \leqslant K_{r}$, the Zolotarev polynomial $Z_{B}(x)$ is a properly rescaled and dylated Chebyshev polynomial

$$
\begin{equation*}
Z_{B}(x)=\lambda_{B}^{-(r+1)} C_{r}\left(\lambda_{B} x\right), \quad \lambda_{B}:=\frac{L_{r}}{B}, \tag{0.4}
\end{equation*}
$$

with $r+1$ points of alternance $\left\{\tau_{i}(B)=\lambda_{B} T_{i}\right\}_{i=0}^{r}$ on the interval $\left[0, \tau_{r}(B)\right]$. In the case $B \in\left[L_{r}, K_{r}\right]$, the collection $\left\{\tau_{i}(B)\right\}_{i=0}^{r}$ is the set of alternance points of the function $Z_{B}$ on the entire interval [0, 1]:

$$
\begin{equation*}
Z_{B}\left(\tau_{i}(B)\right)=(-1)^{r+1+i}\left\|Z_{B}\right\|_{\mathbb{C}[0,1]}=(-1)^{r+1+i} B, \quad i=0, \ldots, r . \tag{0.5}
\end{equation*}
$$

For $B>K_{r}$, the Zolotarev polynomial $Z_{B}(t)$ admits an expression in terms of elliptic functions [1, 12].

For $n \in \mathbb{N}$, let us introduce the Sobolev class

$$
\begin{equation*}
W_{\infty}^{n}[a, b]=\left\{f \in \mathbb{C}^{n-1}[a, b] \mid f^{(n-1)} \text { is abs. cont. and }\left\|f^{(n)}\right\|_{\mathbb{1}_{\infty}[a, b]} \leqslant 1\right\} . \tag{0.6}
\end{equation*}
$$

S. Karlin [7, p. 419] showed that the Zolotarev polynomial $Z_{B}$ enjoys the extremal property

$$
\begin{equation*}
(-1)^{r+1+m} Z_{B}^{(m)}(0)=\sup \left\{f^{(m)}(0) \mid f \in W_{\infty}^{r+1}[0,1],\|f\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]} \leqslant B\right\} . \tag{0.7}
\end{equation*}
$$

In view of properties ( 0.5 ) and (0.7), in the case $B \in\left[L_{r}, K_{r}\right]$, the function $Z_{B}$ is extremal in the Kolmogorov-Landau problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W_{\infty}^{r+1}[0,1], \quad\|f\|_{\mathbb{C}[0,1]} \leqslant B \tag{0.8}
\end{equation*}
$$

Definition 0.1. Let $f$ be a continuous function on the interval $[a, b]$. The function

$$
\begin{equation*}
\omega(f ; t)=\sup _{\substack{x, y \in[a, b] \\|x-y| \leqslant t}}|f(x)-f(y)|, \quad t \in[0, b-a], \tag{0.9}
\end{equation*}
$$

is called the modulus of continuity of the function $f$.
The functional class $W_{\infty}^{r+1}[0,1]$ is defined by the constraint $\left\|f^{(r+1)}\right\|_{\mathbb{d}_{\infty}(I)} \leqslant 1$, equivalent to inequalities $\omega\left(f^{(r)}, t\right) \leqslant t$ for all $t \in[0,1]$. In our generalizations, we consider the classes of functions defined by the
continuum of inequalities of the form $\omega\left(f^{(r)}, t\right) \leqslant \omega(t)$, for $t \in[0,1]$ and some fixed concave modulus of continuity $\omega$. Such constraints enable us not only to control upper bounds of the function $f^{(r+1)}$ but also to retain information on the order of growth of the $r$ th derivative $f^{(r)}$.

This discussion leads us to the definition of functional classes $W^{r} H^{\omega}[0,1]$ with a majorizing modulus of continuity and generalizations of Zolotarev polynomials in $W^{r} H^{\omega}[0,1]$.

### 0.2. Functional Classes $W^{r} H^{\omega}[a, b]$

Let us introduce the notion of a concave modulus of continuity on the half-line $\mathbb{R}_{+}$.

Definition 0.2. A function $\omega(\cdot): \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$, is called a concave modulus of continuity on $\mathbb{R}_{+}$, if the following conditions are satisfied:
(1) $\omega(0)=0$;

$$
\begin{align*}
& \omega\left(t_{1}\right) \leqslant \omega\left(t_{2}\right), \quad \text { if } \quad 0 \leqslant t_{1} \leqslant t_{2} ;  \tag{2}\\
& \omega\left(\alpha t_{1}+(1-\alpha) t_{2}\right) \geqslant \alpha \omega\left(t_{1}\right)+(1-\alpha) \omega\left(t_{2}\right), \quad \text { for all } \quad \alpha \in[0,1] \tag{3}
\end{align*}
$$

$$
\text { and } \quad t_{1}, t_{2} \in \mathbb{R}_{+}
$$

Definition 0.3. Let $\omega(t)$ be a concave modulus of continuity on $\mathbb{R}_{+}$. The functional class $W^{r} H^{\omega}[a, b]$ is defined as

$$
\begin{equation*}
W^{r} H^{\omega}[a, b]:=\left\{x \in \mathbb{C}^{r}[a, b] \mid \omega\left(x^{(r)} ; t\right) \leqslant \omega(t), t \in[0, b-a]\right\} . \tag{0.11}
\end{equation*}
$$

In the case $r=0$ we also use the notations

$$
\begin{equation*}
H^{\omega}[a, b]:=W^{0} H^{\omega}[a, b], \quad H_{0}^{\omega}[a, b]:=\left\{f \in H^{\omega}[a, b] \mid f(a)=0\right\} . \tag{0.12}
\end{equation*}
$$

The standard Sobolev class $W_{\infty}^{r+1}[a, b]$ is a particular case of the class $W^{r} H^{\tilde{\omega}}[a, b]$ with $\tilde{\omega}(t)=t$. Another example is provided by the Hölder modulii of continuity $\omega_{\alpha}(t)=t^{\alpha}, 0<\alpha \leqslant 1$. In this case, we denote

$$
\begin{equation*}
W^{r} H^{\alpha}[a, b]:=W^{r} H^{\omega_{\alpha}}[a, b] . \tag{0.13}
\end{equation*}
$$

We mention that classes $W^{r} H^{\omega}[a, b]$ were introduced in 1946 by S. M. Nikol'skii [10] in connection with approximation of functions by Fourier sums.

### 0.3. Zolotarev $\omega$-Polynomials

Fix $r, m \in \mathbb{N}: 1 \leqslant m \leqslant r$ and a concave modulus of continuity $\omega$ on $\mathbb{R}_{+}$. Our main goal in this paper is to construct a family $\left\{Z_{B}=Z_{B, r, m, \omega}\right\}_{B>0}$ of functions endowed with the properties
(1) there exist such points $\left\{\tau_{i}(B)\right\}_{i=0}^{r}, 0=\tau_{0}(B)<\cdots<\tau_{r}(B) \leqslant 1$, that

$$
\begin{align*}
& Z_{B}\left(\tau_{i}(B)\right)=(-1)^{i+m}\left\|Z_{B}\right\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]}, \quad i=0, \ldots, r ; \\
& \omega\left(Z_{B}^{(r)} ; t\right)=\omega(t), \quad 0 \leqslant t \leqslant 1 ;  \tag{0.14}\\
& Z_{B}^{(m)}(0)=\sup \left\{f^{(m)}(0) \mid f \in W^{r} H^{\omega}[0,1],\|f\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]} \leqslant B\right\} .
\end{align*}
$$

If $\omega$ is a linear modulus of continuity $\omega_{M}(t)=M t, M>0$, then

$$
\omega\left(f^{(r)} ; t\right)=\omega_{M}(t), \quad t \in[0,1] \Leftrightarrow f^{(r)}(t)=C \pm M t, \quad C \in \mathbb{R}, \quad t \in[0,1],
$$

i.e., $f$ is a polynomial of degree $r+1$ with the leading coefficient $M /(r+1)$ ! Therefore, it is natural that functions $Z_{B}$ with features ( 0.14 ) generalizing the properties of classical Zolotarev polynomials will be called the Zolotarev $\omega$-polynomials.

### 0.4. Organization of the Paper

In Section 1 we list auxiliary results used in our constructions: the Borsuk theorem, the Chebyshev theorem, the Korneichuk lemma with corollaries, and some other special technical propositions.

Section 2 contains the proof of the main result of this paper-Theorem 2.1 describing Zolotarev $\omega$-polynomials $Z_{B}=Z_{B, \omega, r, m}$ of the norm $B$.

A number of corollaries from Theorem 2.1 are derived in Section 3. We show the existence of such a constant $M=M_{\omega, r, m}$ that for all $B>M$, the Zolotarev function $Z_{B}$ is extremal in the Kolmogorov-Landau problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\omega}[0,1], \quad\|f\|_{\mathbb{C}[0,1]} \leqslant B \tag{0.15}
\end{equation*}
$$

In the special case of the Hölder modulus of continuity $\omega_{\alpha}(t)=t^{\alpha}$, we construct the Chebyshev $\omega$-polynomial $C(x)=C_{\alpha, r, m}(x)$ with a complete $(r+2)$-alternance and extremal in (0.15) for $B=L:=\|C\|_{\mathbb{C}[0,1]}$. Then, we show the extremality of $Z_{B}$ in the problem (0.15) for all $B \geqslant L$.

For all sufficiently large $B>0$, we demonstrate the continuous dependence of the alternance points $\left\{\tau_{i}(B)\right\}_{i=0}^{r}$ of $Z_{B}$ on $B$ and the uniqueness of solutions of the problem (0.15).

Finally, using specific features of the class $W^{2} H^{\omega}[0,1]$, we also describe the complete (for all $B>0$ ) set of extremal functions in the problem (0.15) for $r=2$.

## 1. AUXILIARY RESULTS

The Korneichuk lemma describes extremal functions in the problem

$$
\begin{equation*}
\int_{a}^{b} h(t) \psi(t) d t \rightarrow \sup , \quad h \in H^{\omega}[a, b], \tag{1.1}
\end{equation*}
$$

where $\psi$ is the derivative of a simple kernel on $[a, b]$.
Definition 1.1. Let the kernel $\psi(\cdot) \in \mathbb{L}_{1}[a, b]$ be endowed with the properties: for some $a^{\prime}, b^{\prime}: a<a^{\prime} \leqslant b^{\prime}<b$,

$$
\begin{array}{lll}
\text { (i) } & \psi(x)<0, & \text { for a.e. } \\
\text { (ii) } & x(x)=0, & \text { for a.e. } \\
\text { (ii) }] ;\left[a^{\prime}, b^{\prime}\right] ; \\
\text { (ii) } & \psi(x)>0, & \text { for a.e. } \\
& x \in\left[b^{\prime}, b\right] ; \\
\text { (iv) } & \int_{a}^{b} \psi(x) d x=0 .
\end{array}
$$

Then the kernel $\Psi(x)=\chi \int_{a}^{x} \psi(t) d t, a \leqslant x \leqslant b, \chi \in\{-1,1\}$, fixed, is called a simple kernel.

Notice that for any simple kernel $\Psi$, the equation $|\Psi(t)|=y$, for $0<y<$ $\|\Psi\|_{\mathbb{C}[a, b]}$, has precisely two solutions: $\alpha_{y} \in\left(a, a^{\prime}\right)$ and $\beta_{y} \in\left(b^{\prime}, b\right)$. The quantitative solution of the problem (1.1) will be given in terms of the rearrangement of the simple kernel $\Psi$.

Definition 1.2. Let $\Psi(x), a \leqslant x \leqslant b$, be a simple kernel. Let the function $r:\left[a,\left(a^{\prime}+b^{\prime}\right) / 2\right] \rightarrow\left[\left(a^{\prime}+b^{\prime}\right) / 2, b\right]$ be derived from equations

$$
\begin{align*}
\Psi(t) & =\Psi(r(t)), & & t \in\left[a, a^{\prime}\right], \\
r(t) & =a^{\prime}+b^{\prime}-t, & & t \in\left[a^{\prime},\left(a^{\prime}+b^{\prime}\right) / 2\right] . \tag{1.3}
\end{align*}
$$

Then, the rearrangement $\mathfrak{R}(\Psi ; t), 0 \leqslant t \leqslant b-a$, of the simple kernel $\Psi(t)$ is defined as

$$
\mathfrak{R}(\Psi ; t):=\left\{\begin{array}{cl}
\|\Psi\|_{\mathbb{C}[a, b]}, & t \in\left[0, b^{\prime}-a^{\prime}\right],  \tag{1.4}\\
\left|\Psi\left(y_{t}\right)\right|, & t \in\left(b^{\prime}-a^{\prime}, b-a\right], \\
\text { where } \quad y_{t} \in\left[a, a^{\prime}\right] & \text { is such that } r\left(y_{t}\right)-y_{t}=t .
\end{array}\right.
$$

We also need the following properties of concave modulii of continuity $\omega$ [9, pp. 263, 264].

Proposition 1.1. Let $\omega$ be a concave modulus of continuity on $\mathbb{R}_{+}$. Then,
(a) at any point $x>0, \omega$ has one-sided derivatives

$$
\omega_{-}^{\prime}(x)=\lim _{h \rightarrow 0+} \frac{\omega(x)-\omega(x-h)}{h}, \quad \omega_{+}^{\prime}(x)=\lim _{h \rightarrow 0+} \frac{\omega(x+h)-\omega(x)}{h} ;
$$

(b) each of the functions $\omega_{+}^{\prime}$ and $\omega_{-}^{\prime}$ does not increase on $(0,+\infty)$, and

$$
\omega_{+}^{\prime}(x) \leqslant \omega_{-}^{\prime}(x), \quad x>0
$$

(c) $\omega$ is an absolutely continuous function on $\mathbb{R}_{+}$.

In this paper we make the following choice from the equivalence class of summable functions defining the nonincreasing derivative $\omega^{\prime}$ everywhere on $\mathbb{R}_{+}$.

Definition 1.3. Let $\omega$ be a concave modulus of continuity on $\mathbb{R}_{+}$. We put

$$
\begin{equation*}
\omega^{\prime}(u):=\frac{1}{2}\left[\omega_{+}^{\prime}(u)+\omega_{-}^{\prime}(u)\right], \quad u>0 . \tag{1.5}
\end{equation*}
$$

The following result [9, pp.302-307] describes the derivative of extremal functions of the problem (1.1).

Lemma 1.2. Let $\Psi(t):=\chi \int_{a}^{t} \psi(y) d y, a \leqslant t \leqslant b, \chi \in\{-1,1\}$, be a simple kernel whose derivative satisfies (1.2). Let the function $r:[a, c] \rightarrow[c, b]$, $c:=\left(a^{\prime}+b^{\prime}\right) / 2$, be defined by (1.3), and the rearrangement $\mathfrak{R}(\Psi ; t)$ be introduced in (1.4). Let $\omega(t)$ be a concave modulus of continuity on $[0, b-a]$. Then,

$$
\begin{equation*}
M_{\omega}(\psi):=\sup _{f \in H^{\omega}[a, b]} \int_{a}^{b} f(t) \psi(t) d t=\int_{0}^{b-a} \mathfrak{R}(\Psi ; t) \omega^{\prime}(t) d t \tag{1.6}
\end{equation*}
$$

and the upper bound in (1.6) is attained on the functions whose derivative is given by the formula

$$
\frac{d}{d x} f_{0}(x)= \begin{cases}\omega^{\prime}(r(x)-x), & a \leqslant x \leqslant c  \tag{1.7}\\ \omega^{\prime}\left(x-r^{-1}(x)\right), & c \leqslant x \leqslant b .\end{cases}
$$

Note that extremal functions of the problem (1.1) are determined up to a constant, since $\int_{a}^{b} \psi(t) d t=0$. Therefore,

$$
\begin{equation*}
\sup _{h \in H^{\oplus}[a, b]} \int_{a}^{b} h(t) \psi(t) d t=\sup _{h \in H_{0}^{\infty}[a, b]} \int_{a}^{b} h(t) \psi(t) d t . \tag{1.8}
\end{equation*}
$$

From the formula (1.7) it follows that if $a^{\prime}=b^{\prime}=c$, then the derivative of extremal function of the problem (1.1) is determined uniquely by (1.7).

We mention some corollaries from Lemma 1.2 used in this paper.
Corollary 1.2.1. Let the function $f_{0}$ be defined by (1.7). Then, $f_{0}$ has the full modulus of continuity on the interval $[0, b-a]$ :

$$
\begin{equation*}
\omega\left(f_{0} ; t\right)=\omega(t), \quad 0 \leqslant t \leqslant b-a \tag{1.9}
\end{equation*}
$$

Proof. By (1.7), for any $x: 0 \leqslant x \leqslant c:=\frac{1}{2}\left(a^{\prime}+b^{\prime}\right)$, we have

$$
\begin{align*}
f_{0}(r(x))-f_{0}(x) & =\int_{c}^{r(x)} \omega^{\prime}\left(u-r^{-1}(u)\right) d u-\int_{c}^{x} \omega^{\prime}(r(u)-u) d u \\
& =\int_{c}^{x} \omega^{\prime}(r(u)-u) r^{\prime}(u) d u-\int_{c}^{x} \omega^{\prime}(r(u)-u) d u \\
& =\int_{c}^{x} \omega^{\prime}(r(u)-u) d(r(u)-u) \\
& =\omega(r(x)-x) . \tag{1.10}
\end{align*}
$$

It remains to notice that the function $r(t)-t$ increases from 0 to $b-a$, as $t$ decreases from $c$ to 0 .

Corollary 1.2.2. Let $0<\alpha \leqslant 1$. Let $\Psi(t)$ be a simple kernel on $[0, b]$, and $f$ be an extremal function in the problem

$$
\int_{0}^{b} h(t) \Psi^{\prime}(t) d t \rightarrow \sup , \quad h \in H^{\alpha}[0, b] .
$$

Then, for any $\sigma>0$, the function $h_{\sigma}(t)=\sigma^{\alpha} f(t / \sigma)$ is extremal in the problem

$$
\int_{0}^{\sigma b} h(t) \Psi^{\prime}(t / \sigma) d t \rightarrow \sup , \quad h \in H^{\alpha}[0, \sigma b] .
$$

The proof of Corollary 1.2.2 follows either from the form (1.7) of the derivative of extremal function in the problem (1.1) or from the observation

$$
f(t) \in H^{\alpha}[0, b] \Leftrightarrow \sigma^{\alpha} f(t / \sigma) \in H^{\alpha}[0, \sigma b] .
$$

For the proof of the following limiting property of solutions of problems (1.1), the reader is referred to [2].

Lemma 1.3. Let $\mathbb{S}$ be a compact of $\mathbb{R}^{d}$ and the family of simple kernels $\Psi_{s}, s \in \mathbb{S}$ be endowed with the following properties.
(i) The endpoints $a_{s}$ and $b_{s}$ are continuous functions of $s$ on $\mathbb{S}$, and

$$
a_{s}<a<b<b_{s}, \quad s \in \mathbb{S}, \quad \text { for some } \quad a<b .
$$

(ii) The zero-interval of the kernel $\psi_{s}$ degenerates into a point, i.e., $a_{s}^{\prime}=b_{s}^{\prime}$, for all $s \in \mathbb{S}$.
(iii) The family $\left\{\psi_{s}(t)=\Psi_{s}^{\prime}(t)\right\}_{s \in \mathbb{S}}$ depends continuously on $s$ on $\mathbb{S}$ in the integral metrics in the following sense: for all $s \in \mathbb{S}$,

$$
\left\|\bar{\psi}_{s^{\prime}}-\bar{\psi}_{s}\right\|_{\mathbb{1}_{1}[a, b]} \rightarrow 0, \quad \text { as } \quad s^{\prime} \rightarrow s,
$$

where

$$
\bar{\psi}_{s}(x):=\psi_{s}\left(\frac{b_{s}-a_{s}}{b-a}(x-a)+a_{s}\right), \quad a \leqslant x \leqslant b, \quad s \in \mathbb{S} .
$$

Let $x_{s}$ be the solution of the problem

$$
\int_{a_{s}}^{b_{s}} f(t) \psi_{s}(t) d t \rightarrow \sup , \quad f \in H^{\omega}\left[a_{s}, b_{s}\right], \quad f\left(a_{s}\right)=0 .
$$

Then, functions $x_{s}$ depend continuously on $s$ on $\mathbb{S}$ in the uniform metrics, i.e., for all $s \in \mathbb{S}$,

$$
\left\|x_{s^{\prime}}-x_{s}\right\|_{\mathbb{C}\left[\max \left\{a_{s}, a_{s}\right\}, \min \left\{b_{s}, b_{s}\right\}\right]} \rightarrow 0, \quad \text { as } \quad s^{\prime} \rightarrow s .
$$

The proof of Theorem 2.1 is based on the following topological result known as the Borsuk Antipodality Theorem (cf. [5], [6]).

Theorem 1.4. Let $\mathbb{S}^{n}=\left\{\xi: \xi \in \mathbb{R}^{n+1} \mid\|\xi\|=r\right\}$, where $\|\cdot\|$ is some norm in $\mathbb{R}^{n+1}$, and let $\eta: \mathbb{S}^{n} \rightarrow \mathbb{R}^{n}, \eta(\xi)=\left\{\eta_{1}(\xi), \eta_{2}(\xi), \ldots, \eta_{n}(\xi)\right\}$, be a continuous and odd $(\eta(-\xi)=-\eta(\xi))$ vector field on $\mathbb{S}^{n}$. Then, there exists a vector $\bar{\xi} \in \mathbb{S}^{n}$ such that $\eta(\bar{\xi})=0$.

The polynomial of the best approximation for a given continuous function is characterized as follows [9, p. 48].

Theorem 1.5. Let $f \in \mathbb{C}[a, b]$. Then,
(a) there exists a unique polynomial $p_{f}(t)=\sum_{i=0}^{n} a_{i}(f) t^{i}$ of the best approximation for $f$ on the interval $[a, b]$ among the polynomials of degree $n$, i.e.,

$$
\left\|f-p_{f}\right\|_{\mathbb{C}[a, b]}=\min _{p \in \mathscr{P}_{n}}\|f-p\|_{\mathbb{C}[a, b]},
$$

where $\mathscr{P}_{n}$ is the linear space of polynomials of degree $n$;
(b) the polynomial $p_{f}$ is the polynomial of the best approximation for $f$ among the polynomials of degree $n$, if and only if there exist $n+2$ points $\left\{x_{k}\right\}_{k=1}^{n+2}, a \leqslant x_{1}<x_{2}<\cdots<x_{n+2} \leqslant b$, such that

$$
\begin{equation*}
\left(f-p_{f}\right)\left(x_{i}\right)=(-1)^{i} \xi\left\|f-p_{f}\right\|_{\mathbb{C}[a, b]}, \quad i=1, \ldots, n+2 \tag{1.11}
\end{equation*}
$$

where $\xi=\xi(f) \in\{-1,1\}$, fixed.

Proposition 1.6. Let $f \in \mathbb{C}^{r}[a, b]$. If f has $r$ zeroes (counting multiplicities), then

$$
\begin{equation*}
\left\|f^{(k)}\right\|_{\mathbb{C}[a, b]} \leqslant[b-a]^{r-k}\left\|f^{(r)}\right\|_{\mathbb{C}[a, b]}, \quad k=0, \ldots, r . \tag{1.12}
\end{equation*}
$$

Proof. By Rolle's theorem, the derivative $f^{(k)}(t)$ has a zero $\xi_{k}$ on $[a, b]$ for $k=0, \ldots, r-1$. Then, $f^{(k)}(x)=\int_{\xi_{k}}^{x} f^{(k+1)}(t) d t, a \leqslant x \leqslant b, k=0, \ldots, r-1$. Thus,

$$
\begin{equation*}
\left\|f^{(k)}\right\|_{\mathbb{C}[a, b]} \leqslant(b-a)\left\|f^{(k+1)}\right\|_{\mathbb{C}[a, b]}, \tag{1.13}
\end{equation*}
$$

implying (1.12).
We also need the following result [9, p. 92] on the existence of a polynomial perfect spline satisfying the zero boundary conditions.

Proposition 1.7. Let $r \in \mathbb{N}$. There exists a unique perfect polynomial spline

$$
Y_{r}(x)=\frac{x^{r}}{r!}+\frac{2}{r!} \sum_{i=1}^{r}(-1)^{i}\left(x-t_{i}\right)_{+}^{r}+\sum_{i=0}^{r-1} a_{i} x^{i}
$$

with $r$ knots $\left\{t_{i}\right\}_{i=1}^{r}, 0<t_{1}<\cdots<t_{r}<1$, satisfying the boundary conditions $Y_{r}^{(k)}(0)=Y_{r}^{(k)}(1)=0, k=0, \ldots, r-1$. In addition, $Y_{r}(x)>0, x \in(0,1)$.

The following two results play an important role in the final phase of the proof of Theorem 2.1.

Proposition 1.8. Let $f \in W^{r} H^{\omega}[0,1]$. Then, there exist such constants $E_{1}=E_{1}(r)$ and $E_{2}=E_{2}(r, \omega)$ that

$$
\begin{equation*}
\left|f^{(r)}(0)\right| \leqslant E_{1}\|f\|_{\mathbb{L}_{1}[0,1]}+E_{2} . \tag{1.14}
\end{equation*}
$$

Proof. Let $Y_{r}$ be the perfect spline from Proposition 1.7. Then,

$$
\begin{align*}
\|f\|_{\mathbb{L}_{1}[0,1]} & \geqslant \int_{0}^{1} f(x) Y_{r}^{(r)}(x) d x=(-1)^{r} \int_{0}^{1} f^{(r)}(x) Y_{r}(x) d x \\
& =(-1)^{r} \int_{0}^{1}\left[f^{(r)}(x)-f^{(r)}(0)\right] Y_{r}(x) d x+(-1)^{r} f^{(r)}(0) \int_{0}^{1} Y_{r}(x) d x \tag{1.15}
\end{align*}
$$

Thus, using the inclusion $f^{(r)} \in H^{\omega}[0,1]$ and the inequality (1.15), we obtain the estimate (1.14) with $E_{1}:=\left\|Y_{r}\right\|_{\mathbb{L}_{1}[0,1]}^{-1}$ and $E_{2}:=\left\|Y_{r}\right\|_{\mathbb{L}_{1}[0,1]}^{-1}$. $\left\|\omega \cdot Y_{r}\right\|_{\mathbb{C}[0,1]}$.

Proposition 1.9. Let $A>1$, $\omega$ be a concave modulus of continuity, and the function $f(t) \in \mathbb{A C}^{r+1}[0, A]$ be endowed with the properties
(i) $f^{(r)}(t)>0, \quad$ for a.e. $t \in[0, A]$;
(ii) $f^{(r-1)} \in H^{\omega}[0,1]$;
(iii) $f^{(r)}(t)=1, \quad t \in[1, A]$;
(iv) f has r zeroes $\left\{\eta_{l}^{0}\right\}_{l=1}^{r}$ satisfying inequalities

$$
0 \leqslant \eta_{r}^{0}<\eta_{r-1}^{0}<\cdots<\eta_{2}^{0} \leqslant 1<\eta_{1}^{0}:=A .
$$

Then, for each $k=1, \ldots, r-1$, the derivative $f^{(k)}$ has precisely $r-k$ simple zeroes $\left\{\eta_{l}^{k}\right\}_{l=1}^{r-k}$,

$$
\begin{equation*}
0 \leqslant \eta_{r-k}^{k}<\eta_{r-k-1}^{k}<\cdots<\eta_{2}^{k}<\eta_{1}^{k}, \tag{1.17}
\end{equation*}
$$

and there exist constants $E_{r, k}$ such that

$$
\begin{equation*}
\eta_{1}^{k}>E_{r, k} A>1, \quad 0 \leqslant k \leqslant r-1, \tag{1.18}
\end{equation*}
$$

for all sufficiently large A's.
Proof. By the property (1.16), (iv), $f^{(k)}$ has at least $r-k$ distinct zeroes on [ $0, A$ ] for $1 \leqslant k \leqslant r-1$. On the other hand, by (1.16), (i), $f^{(r-1)}$ is monotone on $[0, A]$. Thus, $f^{(k)}$ can have at most $r-k$ zeroes counting multiplicities. Therefore, Rolle's theorem implies that $f^{(k)}$ has precisely $r-k$ simple zeroes $\left\{\eta_{i}^{k}\right\}_{i=1}^{r-k}$ enumerated in the decreasing order as in (1.17). We also observe that by (1.16), (iv) and Rolle's theorem, zeroes $\left\{\eta_{i}^{k}\right\}_{i=2}^{r-k}$ lie on the interval $[0,1]$.

The verification of the property (1.18) of rightmost zeroes $\left\{\eta_{1}^{k}\right\}_{k=0}^{r-1}$ proceeds by induction.

For $k=0$ the statement is true by (1.16), (iv): $\eta_{1}^{0}:=A$.
Suppose that we have proved the statement for any $k=0, \ldots, n \leqslant r-2$, i.e.,

$$
\begin{equation*}
\eta_{1}^{k}>E_{r, k} \cdot A>1, \quad k=0, \ldots, n . \tag{1.19}
\end{equation*}
$$

Let us prove the property (1.18) for $k=n+1$.
First, $f^{(n)}\left(\eta_{2}^{n}\right)=f^{(n)}\left(\eta_{1}^{n}\right)=0$. Therefore,

$$
\begin{equation*}
0=\int_{\eta_{2}^{n}}^{\eta_{1}^{n}} f^{(n+1)}(\xi) d \xi=\int_{\eta_{2}^{n}}^{\eta_{1}^{n+1}} f^{(n+1)}(\xi) d \xi+\int_{\eta_{1}^{n+1}}^{\eta_{1}^{n}} f^{(n+1)}(\xi) d \xi, \tag{1.20}
\end{equation*}
$$

where $\eta_{1}^{n+1}$ is the rightmost zero of $f^{(n+1)}(t)$. By Rolle's theorem, it lies between $\eta_{1}^{n}$ and $\eta_{2}^{n}$.

By Rolle's theorem, the other $r-n-2$ zeroes belong to the interval [ $0, \eta_{2}^{n}$ ]. Thus, the function $f^{(n+1)}(t)$ changes its sign on the interval $\left[\eta_{2}^{n}, \eta_{1}^{n}\right]$ only at the point $\eta_{1}^{n+1}$.

Therefore, we can infer from (1.20) that

$$
\begin{equation*}
\int_{\eta_{2}^{n}}^{\eta_{1}^{n+1}}\left|f^{(n+1)}(\xi)\right| d \xi=\int_{\eta_{1}^{n+1}}^{\eta_{1}^{n}}\left|f^{(n+1)}(\xi)\right| d \xi=\frac{1}{2}\left\|f^{(n+1)}\right\|_{\mathbb{1}_{1}\left[\eta_{2}^{n}, \eta_{1}^{n}\right]} . \tag{1.21}
\end{equation*}
$$

Let

$$
\begin{equation*}
I_{k}:=\min _{p \in P_{k}}\|p\|_{\mathbb{1}_{1}[0,1]}, \quad k \in N \tag{1.22}
\end{equation*}
$$

where $P_{k}$ is the space of all polynomials of degree $k$ with the leading coefficient $\pm 1 / k$ !. Then,

$$
\begin{equation*}
\min _{p \in P_{k}}\|p\|_{\mathbb{L}_{1}[a, b]}=(b-a)^{k+1} I_{k} . \tag{1.23}
\end{equation*}
$$

By (1.16), (iii), $f^{(r)}(t)=1, t \in[1, A]$, i.e., $f^{(n+1)}(t)$ is a polynomial of degree $r-n-1$ on the interval $[1, A]$ with the leading coefficient $1 /(r-n-1)$ !. Thus, by (1.23),

$$
\begin{equation*}
\left\|f^{(n+1)}\right\|_{\mathrm{L}_{1}\left[1, \eta_{1}^{n}\right]} \geqslant I_{r-n-1}\left(\eta_{1}^{n}-1\right)^{r-n} . \tag{1.24}
\end{equation*}
$$

Consecutively using the equalities (1.21), the inclusion $\eta_{2}^{n} \in[0,1]$, the inequality (1.24), and the inductive assumption (1.19) for $k=n$, we derive the estimates

$$
\begin{align*}
\int_{\eta_{2}^{n}}^{\eta_{1}^{n+1}}\left|f^{(n+1)}(\xi)\right| d \xi & =\frac{1}{2}\left\|f^{(n+1)}\right\|_{\mathbb{1}_{1}\left[\eta_{2}^{n}, \eta_{1}^{n}\right]} \geqslant \frac{1}{2}\left\|f^{(n+1)}\right\|_{\mathbb{1}_{1}\left[1, \eta_{1}^{n}\right]} \\
& \geqslant \frac{1}{2} I_{r-n-1}\left(\eta_{1}^{n}-1\right)^{r-n} \geqslant \frac{1}{2} I_{r-n-1}\left(E_{r, n} \cdot A-1\right)^{r-n} . \tag{1.25}
\end{align*}
$$

In a more compact form,

$$
\begin{equation*}
\left\|f^{(n+1)}\right\|_{\mathbb{1}_{1}\left[\eta_{2}^{n}, \eta_{1}^{n+1}\right]} \geqslant \frac{1}{2} I_{r-n-1}\left(E_{r, n} \cdot A-1\right)^{r-n} . \tag{1.26}
\end{equation*}
$$

We have already shown that each of the functions $f^{(k)}$ has a zero on $[0, A]$ for $k=0, \ldots, r-1$. Thus, applying Proposition 1.6 and using properties (1.16), (ii), (iii) of the function $f$, we obtain the inequality

$$
\begin{equation*}
\left\|f^{(n+1)}\right\|_{\mathbb{C}[0, A]} \leqslant A^{r-n-2}\left\|f^{(r-1)}\right\|_{\mathbb{C}[0, A]} \leqslant A^{r-n-2}(A+\omega(1)) \leqslant 2 A^{r-n-1} \tag{1.27}
\end{equation*}
$$

for $A>\omega(1)$. Consequently,

$$
\begin{equation*}
\left\|f^{(n+1)}\right\|_{\mathbb{L}_{1}\left[\eta_{2}^{n}, \eta_{1}^{n+1}\right]} \leqslant\left\|f^{(n+1)}\right\|_{\mathbb{C}[0, A]}\left(\eta_{1}^{n+1}-\eta_{2}^{n}\right) \leqslant 2 A^{r-n-1}\left(\eta_{1}^{n+1}-\eta_{2}^{n}\right) . \tag{1.28}
\end{equation*}
$$

Combining the estimates (1.26) from below and (1.28) from above for the integral norm of the function $f^{(n+1)}(t)$, we derive the following estimate for the length of the interval $\left[\eta_{2}^{n}, \eta_{1}^{n+1}\right]$ :

$$
\begin{equation*}
\eta_{1}^{n+1}-\eta_{2}^{n} \geqslant \frac{1}{4} I_{r-n-1} A^{n-r+1}\left(E_{r, n} \cdot A-1\right)^{r-n} . \tag{1.29}
\end{equation*}
$$

Due to the inclusion $\eta_{2}^{n} \in[0,1]$, the inequality (1.29) implies that for all sufficiently large $A$ 's,

$$
\begin{equation*}
\eta_{1}^{n+1} \geqslant \frac{1}{4} I_{r-n-1} A^{n-r+1}\left(E_{r, n} \cdot A-1\right)^{r-n}-1 \geqslant E_{r, n+1} A>1, \tag{1.30}
\end{equation*}
$$

with the constant $E_{r, n+1}$ depending only on $r, n$.
In conclusion, we state the properties of generating kernels $K(t)$ and $F(t)$ (see, e.g., [8]).

Let $r, m: 0<m \leqslant r$, be integers.
Let $\left\{\tau_{i}\right\}_{i=0}^{r}$ be such that

$$
\begin{equation*}
0=\tau_{0}<\tau_{1}<\cdots<\tau_{r} \leqslant 1 . \tag{1.31}
\end{equation*}
$$

Derive $\left\{\alpha_{i}=\alpha_{i}\left(\tau_{0}, \ldots, \tau_{r}, m\right)\right\}_{i=0}^{r}$ from the system of linear equations

$$
\begin{equation*}
\sum_{i=0}^{r} \alpha_{i} \tau_{i}^{k}=\delta_{m, k}, \quad k=0, \ldots, r . \tag{1.32}
\end{equation*}
$$

Put

$$
\begin{align*}
& K(u)=-\frac{1}{(r-1)!} \sum_{i=1}^{r} \alpha_{i}\left(\tau_{i}-u\right)_{+}^{r-1},  \tag{1.33}\\
& F(u)=\frac{1}{r!} \sum_{i=1}^{r} \alpha_{i}\left(\tau_{i}-u\right)_{+}^{r} .
\end{align*}
$$

Proposition 1.10. Let $r, m \in \mathbb{N}: 0<m \leqslant r$, the points $\left\{\tau_{i}\right\}_{i=0}^{r}$ be as in (1.31), the coefficients $\left\{\alpha_{i}\right\}_{i=0}^{r}$ be defined in (1.32), and the kernels $K(t)$, $F(t)$ be defined by (1.33). Then,
I. $\operatorname{sign} \alpha_{i}=(-1)^{i+m}, i=0, \ldots, r$;
II. for $0<m<r$, the kernel $F(t)$ is simple on $\left[0, \tau_{r}\right]$, and for some $c \in(0,1)$,
sign $K(t)=(-1)^{r+m}, t \in(0, c) ; \quad \operatorname{sign} K(t)=(-1)^{r+m+1}, \quad t \in(c, 1) ;$
III. for $m=r, K(t)$ does not change the sign: $K(t)<0, t \in[0,1)$.

## 2. CONSTRUCTION OF ZOLOTAREV $\omega$-POLYNOMIALS

2.1. Sufficient Conditions of Extremality in the Kolmogorov-Landau Problem

Fix $r, m \in \mathbb{N}: 0<m \leqslant r$. Let $0=: \tau_{0}<\tau_{1}<\tau_{2}<\cdots \tau_{r}:=b \leqslant 1$.
Let $\left\{\alpha_{i}\right\}_{i=0}^{r}$ be the solutions of the following system of linear equations:

$$
\begin{equation*}
\sum_{i=0}^{r} \alpha_{i} \tau_{i}^{k}=\delta_{m, k}, \quad k=0, \ldots, r . \tag{2.1}
\end{equation*}
$$

In (2.1), we follow the convention $\left[\tau_{0}\right]^{0}=0^{0}:=1$. Put

$$
\begin{align*}
& K(u)=-\frac{1}{(r-1)!} \sum_{i=0}^{r} \alpha_{i}\left(\tau_{i}-u\right)_{+}^{r-1}, \\
& F(u)=\frac{1}{r!} \sum_{i=0}^{r} \alpha_{i}\left(\tau_{i}-u\right)_{+}^{r} . \tag{2.2}
\end{align*}
$$

Fix $f \in W^{r} H^{\omega}[0,1]$. The Taylor's formula reads

$$
\begin{equation*}
f(\tau)=\sum_{k=0}^{r-1} \frac{f^{(k)}(0)}{k!} \tau^{k}+\frac{1}{(r-1)!} \int_{0}^{1} f^{(r)}(u)(\tau-u)_{+}^{r-1} d u, \quad 0 \leqslant \tau \leqslant 1 . \tag{2.3}
\end{equation*}
$$

We distinguish two cases in deriving the formula for $f^{(m)}(0)$.
Case 1. $0<m<r$.
From (2.1)-(2.3) we find the formula for the value of the $m$ th derivative $f^{(m)}$ at the origin:

$$
\begin{equation*}
f^{(m)}(0)=m!\sum_{i=0}^{r} \alpha_{i} f\left(\tau_{i}\right)+m!\int_{0}^{b} f^{(r)}(u) K(u) d u . \tag{2.4}
\end{equation*}
$$

By Proposition 1.10, the kernel $F(t)=\int_{1}^{t} K(y) d y$ is simple in the sense of Definition 1.1. Therefore, by Korneichuk's Lemma 1.2,

$$
\begin{equation*}
\sup _{h \in H^{\omega}[0, b]} \int_{0}^{b} h(t) K(t) d t=\sup _{h \in H_{0}^{\omega}[0, b]} \int_{0}^{b} h(t) K(t) d t=\int_{0}^{b} \mathfrak{R}(F ; t) \omega^{\prime}(t) d t, \tag{2.5}
\end{equation*}
$$

where the classes $H_{0}^{\omega}[a, b]$ are defined in (0.12), and the rearrangements $\mathfrak{R}(\Psi ; t)$ of simple kernels $\Psi$ are introduced in (1.4). The Korneichuk lemma also provides the formula for the derivative of the function $h^{*}(t)$ realizing the supremum in (2.5):

$$
\frac{d}{d t} h^{*}(t)= \begin{cases}(-1)^{r+m+1} \omega^{\prime}(\rho(t)-t), & 0 \leqslant t \leqslant c  \tag{2.6}\\ (-1)^{r+m+1} \omega^{\prime}\left(t-\rho^{-1}(t)\right), & c \leqslant t \leqslant \tau_{r}\end{cases}
$$

where $c$ is a unique zero of the kernel $K(t)$ on the open interval $(0, b)$, and the function $\rho:[0, c] \rightarrow[c, b]$ is derived from the equations

$$
\begin{equation*}
F(t)=F(\rho(t)), \quad 0 \leqslant t \leqslant c . \tag{2.7}
\end{equation*}
$$

From (2.4) and (2.5) we obtain the estimate

$$
\begin{equation*}
\left|f^{(m)}(0)\right| \leqslant m!\left(\sum_{i=0}^{r}\left|\alpha_{i}\right|\right)\|f\|_{\mathbb{C}[0,1]}+m!\int_{0}^{b} \mathfrak{R}(F ; t) \omega^{\prime}(t) d t . \tag{2.8}
\end{equation*}
$$

Case 2. $m=r$.
In this case, by (2.1), $\int_{0}^{b} K(u) d u=-1 / r!\sum_{i=0}^{r} \alpha_{i} \tau_{i}^{r}=-1 / r!$. Therefore, by (2.1)-(2.3),

$$
\begin{equation*}
f^{(r)}(0)=r!\sum_{i=0}^{r} \alpha_{i} f\left(\tau_{i}\right)+r!\int_{0}^{b}\left[f^{(r)}(u)-f^{(r)}(0)\right] K(u) d u \tag{2.9}
\end{equation*}
$$

Notice that $f^{(r)}(x)-f^{(r)}(0) \in H_{0}^{\omega}[0,1]$, if $f \in W^{r} H^{\omega}[0,1]$. In Proposition 1.10 we showed that $K(u)<0,0 \leqslant u<b$. Therefore,
$\sup _{h \in H_{0}^{s}[0,1]} \int_{0}^{b} h(u) K(u) d u=-\int_{0}^{b} \omega(u) K(u) d u=\int_{0}^{b} \omega^{\prime}(u) F(u) d u$.
The equality sign is attained in (2.10), if and only if

$$
\begin{equation*}
f^{(r)}(u)-f^{(r)}(0)=-\omega(u), \quad 0 \leqslant u \leqslant b . \tag{2.11}
\end{equation*}
$$

Consequently, by (2.9) and (2.10),

$$
\begin{equation*}
\left|f^{(r)}(0)\right| \leqslant r!\left(\sum_{i=0}^{r}\left|\alpha_{i}\right|\right)\|f\|_{\mathbb{C}[0,1]}+r!\int_{0}^{b} \omega^{\prime}(t) F(t) d t \tag{2.12}
\end{equation*}
$$

By Proposition 1.10, in both cases $(-1)^{i+m} \alpha_{i}>0, i=0, \ldots, r$. Combining these two cases and taking into account our observation (2.5), we give sufficient conditions for a function $f \in W^{r} H^{\omega}[0,1]$ to realize the equality sign in inequalities (2.8) for $0<m<r$ and (2.12) for $m=r$ :

$$
\begin{align*}
& \text { (i) } f\left(\tau_{i}\right)=(-1)^{i+m}\|f\|_{\mathbb{C}[0, b]}, \quad i=0, \ldots, r \text {; }  \tag{i}\\
& \text { (ii) } \sup _{h \in H_{0}^{\infty}[0, b]} \int_{0}^{b} h(x) K(x) d x=\int_{0}^{b}\left[f^{(r)}(x)-f^{(r)}(0)\right] K(x) d x . \tag{2.13}
\end{align*}
$$

Therefore, the problem is to choose the collection of points $\left\{\tau_{i}\right\}_{i=0}^{r}$ simultaneously endowed with two properties: $\left\{\tau_{i}\right\}_{i=0}^{r}$ are the knots of the generating kernel $K$ for the function $f^{(r)}(x)$ and the alternance points of the function $f$ on the interval $[0, b]$.

### 2.2. Characterization of Zolotarev $\omega$-Polynomials

Theorem 2.1. Let $r, m \in \mathbb{N}: 0<m \leqslant r$, and $B>0$. There exists a set of points $\left\{\tau_{i}(B)=\tau_{i}(B, r, m, \omega)\right\}_{i=0}^{r}, 0=\tau_{0}(B)<\tau_{1}(B)<\cdots<\tau_{r}(B) \leqslant 1$, and the function $Z_{B}=Z_{B, r, m, \omega} \in W^{r} H^{\omega}[0,1]$ with the properties
(i) $\sup _{h \in H_{0}^{\omega}\left[0, \tau_{r}(B)\right]} \int_{0}^{\tau_{r}(B)} h(t) K_{B}(t) d t=\int_{0}^{\tau_{r}(B)}\left[Z_{B}^{(r)}(t)-Z_{B}^{(r)}(0)\right] K_{B}(t) d t$,
where the kernel $K_{B}$ is defined by (2.1), (2.2) for $\left\{\tau_{i}=\tau_{i}(B)\right\}_{i=0}^{r}$;
(ii) $\quad Z_{B}\left(\tau_{i}(B)\right)=(-1)^{i+m}\left\|Z_{B}\right\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]^{2}}=(-1)^{i+m} B, \quad i=0, \ldots, r$;
(iii) if $\tau_{r}(B)<1$, then $\frac{d}{d t} Z_{B}\left(\tau_{r}(B)\right)=0$.

Proof. Fix $A>4$ and $\varepsilon, 0<\varepsilon<1 / r$. Let

$$
\begin{equation*}
\mathbb{S}_{A}^{r}:=\left\{s=\left(s_{1}, \ldots, s_{r+1}\right) \in \mathbb{R}^{r+1}\left|\sum_{i=1}^{r+1}\right| s_{i} \mid=A\right\} \tag{2.15}
\end{equation*}
$$

We generate collections of points $\left\{t_{j}=t_{j}(s)\right\}_{j=0}^{r+1},\left\{\bar{t}_{j}=\bar{t}_{j}(s)\right\}_{j=0}^{r+1},\left\{T_{j}=T_{j}(s)\right\}_{j=0}^{r}$, and $\left\{\tau_{j}=\tau_{j}(s)\right\}_{j=0}^{r}$ :

$$
\begin{array}{lll}
t_{0}(s)=0, & t_{j}(s)=\sum_{i=1}^{j}\left|s_{i}\right|, & j=1, \ldots, r+1 ; \\
\bar{t}_{0}(s)=0, & \bar{t}_{j}(s)=\min \left\{t_{j}(s), 1\right\}, & j=1, \ldots, r+1 ; \\
T_{0}(s)=0, & T_{j}(s)=\frac{t_{j}(s)+\varepsilon j}{1+\varepsilon r}, & j=1, \ldots, r ;  \tag{2.16}\\
\tau_{0}(s)=0, & \tau_{j}(s)=\frac{\bar{t}_{j}(s)+\varepsilon j}{1+\varepsilon r}, & j=1, \ldots, r .
\end{array}
$$

By (2.16),

$$
\begin{equation*}
\tau_{i}(s)-\tau_{i-1}(s) \geqslant \frac{\varepsilon}{1+\varepsilon r}, \quad T_{i}(s)-T_{i-1}(s) \geqslant \frac{\varepsilon}{1+\varepsilon r}, \quad i=1, \ldots, r, \quad s \in \mathbb{S}_{A}^{r}, \tag{2.17}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\bar{t}_{i}(s)-\tau_{i}(s)\right| \leqslant \varepsilon r, \quad\left|T_{i}(s)-t_{i}(s)\right|<\varepsilon r A, \quad i=0, \ldots, r, \quad s \in \mathbb{S}_{A}^{r} . \tag{2.18}
\end{equation*}
$$

Also by (2.16), the points $\left\{\tau_{i}(s)\right\}_{i=0}^{r}$ belong to the interval [0, 1]:

$$
0 \leqslant \tau_{i}(s) \leqslant \frac{\bar{t}_{i}(s)+\varepsilon i}{1+\varepsilon r} \leqslant \frac{1+\varepsilon i}{1+\varepsilon r} \leqslant 1, \quad i=1, \ldots, r, \quad s \in \mathbb{S}_{A}^{r} .
$$

Let $\left\{\alpha_{i}(s)=\alpha_{i}(s, r, m, \varepsilon)\right\}_{i=0}^{r}$ satisfy the system of linear equations

$$
\begin{equation*}
\sum_{i=0}^{r} \alpha_{i}\left[\tau_{i}(s)\right]^{k}=\delta_{m, k}, \quad k=0, \ldots, r \tag{2.19}
\end{equation*}
$$

As before, in (2.19) we follow the convention $\left[\tau_{0}(s)\right]^{0}=0^{0}:=1$.

Let us introduce kernels $K_{s}$ and $F_{s}$ :

$$
\begin{align*}
K_{s}(t) & =-\frac{1}{(r-1)!} \sum_{0=1}^{r} \alpha_{i}(s)\left(t-\tau_{i}(s)\right)_{+}^{r-1}  \tag{2.20}\\
F_{s}(t) & =\frac{1}{r!} \sum_{0=1}^{r} \alpha_{i}(s)\left(t-\tau_{i}(s)\right)_{+}^{r}
\end{align*}
$$

Let the function $f_{s} \in H_{0}^{\omega}\left[0, \tau_{r}(s)\right]$ be extremal in the problem

$$
\begin{equation*}
\int_{0}^{\tau_{r}(s)} h(t) K_{s}(t) d t \rightarrow \sup , \quad h \in H_{0}^{\omega}\left[0, \tau_{r}(s)\right] . \tag{2.21}
\end{equation*}
$$

If $0<m<r$, by Lemma 1.2, the derivative $(d / d x) f_{s}(x)$ is expressed by the formula

$$
\frac{d}{d t} f_{s}(t)= \begin{cases}(-1)^{r+m+1} \omega^{\prime}\left(\rho_{s}(t)-t\right), & 0 \leqslant t \leqslant c(s)  \tag{2.22}\\ (-1)^{r+m+1} \omega^{\prime}\left(t-\rho_{s}^{-1}(t)\right), & c(s) \leqslant t \leqslant \tau_{r}(s),\end{cases}
$$

where $c(s)$ is a unique zero of $K_{s}$ on the open interval $\left(0, \tau_{r}(s)\right)$, and the function $\rho_{s}:[0, c(s)] \rightarrow\left[c(s), \tau_{r}(s)\right]$ is derived from the equations

$$
F_{s}(t)=F_{s}\left(\rho_{s}(t)\right), \quad 0 \leqslant t \leqslant c(s) .
$$

According to (2.11), for $m=r$ we put

$$
\begin{equation*}
f_{s}(t)=-\omega(t), \quad 0 \leqslant t \leqslant \tau_{r}(s) . \tag{2.23}
\end{equation*}
$$

The extension $g_{s}(t)$ of $f_{s}(t)$ from $\left[0, \tau_{r}(s)\right]$ to $[0, A]$ is defined by the formula

$$
g_{s}(t)= \begin{cases}f_{s}(t), & 0 \leqslant t \leqslant \tau_{r}(s),  \tag{2.24}\\ (-1)^{r+m+1}\left[\omega\left(\tau_{r}(s)\right)+t-\tau_{r}(s)\right], & \tau_{r}(s) \leqslant t \leqslant A .\end{cases}
$$

Notice that by the definitions (2.22) and (2.24), the function $g_{s^{*}}(t)$ is monotone on $[0, A]$, and

$$
\begin{equation*}
(-1)^{r+m+1} \frac{d}{d t} g_{s}(t)>0, \quad \text { for a.e. } \quad t \in[0, A] . \tag{2.25}
\end{equation*}
$$

Also by (2.22) and (2.24),

$$
\begin{equation*}
g_{s} \in H^{\tilde{\omega}}[0, A], \quad \tilde{\omega}(t):=\omega(t)+t, \quad t \in \mathbb{R}_{+} . \tag{2.26}
\end{equation*}
$$

Let us introduce the function

$$
\begin{equation*}
V_{s}(x)=\frac{1}{(r-2)!} \int_{0}^{A}(x-t)_{+}^{r-2} g_{s}(t) d t, \quad 0 \leqslant x \leqslant A . \tag{2.27}
\end{equation*}
$$

Notice that $V_{s}^{(r-1)}(x)=g_{s}(x), 0 \leqslant x \leqslant A$, and $V_{s}^{(i)}(0)=0, i=0, \ldots, r-1$.
Let $q_{s}(t)$ be the polynomial of degree $r-1$ interpolating $V_{s}(t)$ at $r$ distinct points $\left\{T_{i}(s)\right\}_{i=1}^{r}$ :

$$
\begin{equation*}
q_{s}\left(T_{i}(s)\right)=V_{s}\left(T_{i}(s)\right), \quad i=1, \ldots, r \tag{2.28}
\end{equation*}
$$

Put

$$
\begin{equation*}
W_{s}(x):=V_{s}(x)-q_{s}(x), \quad 0 \leqslant x \leqslant A . \tag{2.29}
\end{equation*}
$$

By (2.28),

$$
\begin{equation*}
W_{s}\left(T_{i}(s)\right)=0, \quad i=1, \ldots, r . \tag{2.30}
\end{equation*}
$$

By our observation (2.25), sign $W_{s}^{(r)}(t)=\operatorname{sign}(d / d t) g_{s}(t)=(-1)^{r+m+1}$ for a.e. $t \in[0, A]$. Thus, by the Rolle's theorem, all zeroes $\left\{T_{i}(s)\right\}_{i=1}^{r}$ are simple, and

$$
\begin{equation*}
\operatorname{sign} W_{s}(t)=(-1)^{i+m}, \quad t \in\left(T_{i-1}(s), T_{i}(s)\right), \quad i=1, \ldots, r+1 . \tag{2.31}
\end{equation*}
$$

Put

$$
\begin{equation*}
\Delta_{i}(s):=\int_{\bar{t}_{i-1}(s)}^{\bar{t}_{i}(s)}\left|W_{s}(t)\right| d t, \quad i=1, \ldots, r \tag{2.32}
\end{equation*}
$$

Next, for $s=\left(s_{1}, \ldots, s_{r+1}\right) \in \mathbb{S}_{A}^{r}$, we define the function $U_{s}$ on the interval [0, 1]:

$$
\begin{equation*}
U_{s}(t)=(-1)^{i+m}\left[\operatorname{sign} s_{i}\right]\left|W_{s}(t)\right|, \quad \bar{t}_{i-1}(s) \leqslant t \leqslant \bar{t}_{i}(s), \quad i=1, \ldots, r+1 . \tag{2.33}
\end{equation*}
$$

Let

$$
\begin{equation*}
\tilde{H}_{s}(t)=\int_{0}^{t} U_{s}(x) d x, \quad 0 \leqslant t \leqslant 1 \tag{2.34}
\end{equation*}
$$

Let us introduce the constants

$$
\begin{equation*}
C:=A^{r-1}[A+\omega(A)], \quad \Theta=\min \left\{1, r B\left[C+\frac{4 r B}{A}\right]^{-1}\right\} . \tag{2.35}
\end{equation*}
$$

Put

$$
\begin{equation*}
\theta_{s}:=\max \left\{\Theta, \bar{t}_{r}(s)\right\}, \quad s \in \mathbb{S}_{A}^{r} . \tag{2.36}
\end{equation*}
$$

We introduce the polynomial $p_{s}(t)=\sum_{i=0}^{r-1} a_{i}(s) t^{i}$ of the best approximation for the function $\widetilde{H}_{s}(t)$ on the interval $\left[0, \theta_{s}\right]$ :

$$
\begin{equation*}
\left\|\tilde{H}_{s}-p_{s}\right\|_{\mathbb{C}\left[0, \theta_{s}\right]}=\min _{p \in \mathscr{P}_{r-1}}\left\|\tilde{H}_{s}-p\right\|_{\mathbb{C}\left[0, \theta_{s}\right]} \tag{2.37}
\end{equation*}
$$

where $\mathscr{P}_{r-1}$ is the space of polynomials of degree at most $r-1$. Put

$$
\begin{equation*}
H_{s}(t)=\tilde{H}_{s}(t)-p_{s}(t), \quad t \in[0,1] \tag{2.38}
\end{equation*}
$$

and

$$
\begin{equation*}
D(s):=\sum_{i=1}^{r}\left[\operatorname{sign} s_{i}\right] \Delta_{i}(s)-\frac{2 r B}{A} \sum_{i=1}^{r+1} s_{i} . \tag{2.39}
\end{equation*}
$$

The mapping $\kappa: \mathbb{S}_{A}^{r} \rightarrow \mathbb{R}^{r}$ is defined as

$$
\begin{equation*}
\kappa(s)=\left(a_{1}(s), \ldots, a_{r-1}(s), D(s)\right), \quad s \in \mathbb{S}_{A}^{r} \tag{2.40}
\end{equation*}
$$

In the following lemma we prove the continuity of the mapping $\kappa$.
Lemma 2.1.1. Let the mapping $\kappa$ on the sphere $\mathbb{S}_{A}^{r}$ be defined in (2.40). Then, the mapping $s \mapsto \kappa(s), s \in \mathbb{S}_{A}^{r}$, is continuous.

Proof. From inequalities (2.17) it follows that the Vandermonde determinant of the system of linear equations (2.19) never vanishes on $\mathbb{S}_{A}^{r}$. The Kramer's formula for the solution of (2.19) coupled with the continuity of the mapping $s \mapsto\left\{\tau_{i}(s)\right\}_{i=0}^{r+1}$ implies the continuous dependence of coefficients $\left\{\alpha_{i}(s)\right\}_{i=0}^{r}$ on $s$.

Also by (2.19), $\tau_{r}(s) \geqslant r /(1+\varepsilon r)==: d, s \in \mathbb{S}_{A}^{r}$.
Let us introduce the dylated version of the kernel $K_{s}$ :

$$
\begin{equation*}
\hat{K}_{s}(t):=K_{s}\left(\frac{\tau_{r}(s) t}{d}\right), \quad 0 \leqslant t \leqslant d . \tag{2.41}
\end{equation*}
$$

The continuity of the mapping $s \mapsto\left(\left\{\alpha_{i}(s)\right\}_{i=0}^{r}, \tau_{r}(s)\right)$ implies the continuous dependence of the family of kernels $\left\{\hat{K}_{s}\right\}_{s \in \mathbb{S}^{r}}^{A}$ on $s$ in the metrics $\mathbb{L}_{1}[0, d]$ (and even $\mathbb{C}[0, d]$ ). Therefore, we can apply Lemma 1.3 to the family of kernels $K_{s}(t)$ and functions $f_{s}(t)$ extremal in the problem (2.21). Then, Lemma 1.3 and the definition (2.24) of the extension $g_{s}(t)$ guarantee the continuity of the mapping $s \mapsto g_{s}$ in $\mathbb{C}[0, A]$.

Then, by the definition (2.27), the mapping $s \mapsto V_{s}$ is continuous in $\mathbb{C}[0, A]$. From the separation property (2.17) of the points $\left\{T_{i}(s)\right\}_{i=1}^{r}$ and the Lagrange formula for the interpolating polynomial $q_{s}(t)$ we deduce the continuity of the mapping $s \mapsto W_{s}$ in $\mathbb{C}[0, A]$. In particular, there exists such a constant $\mathscr{M}$ that

$$
\begin{equation*}
\left\|U_{s}\right\|_{\mathbb{L}_{\infty}[0,1]}=\left\|W_{s}\right\|_{\mathbb{C}[0,1]} \leqslant \mathscr{M}, \quad \text { for all } \quad s \in \mathbb{S}_{A}^{r} \tag{2.42}
\end{equation*}
$$

Next, using the definitions (2.33) of the function $U_{s}$ and (2.34) of the function $\widetilde{H}_{s}(t)$, we derive the chain of inequalities

$$
\begin{align*}
\left\|\tilde{H}_{s_{1}}-\tilde{H}_{s_{2}}\right\|_{\mathbb{C}[0,1]} & \leqslant\left\|U_{s_{1}}-U_{s_{2}}\right\|_{\mathbb{L}_{1}[0,1]} \\
& \leqslant 2\left(\mathscr{M}\left\|s_{1}-s_{2}\right\| l_{1}^{r+1}+\left\|W_{s_{1}}-W_{s_{2}}\right\|_{\mathrm{L}_{1}[0,1]}\right), \tag{2.43}
\end{align*}
$$

which proves the continuity of the mapping $s \mapsto \tilde{H}_{s}$ in $\mathbb{C}[0,1]$. Then, the continuous dependence on $s$ of coefficients $\left\{a_{i}(s)\right\}_{i=0}^{r}$ of the polynomial $p_{s}$ of the best approximation for $\tilde{H}_{s}$ on $\left[0, \theta_{s}\right]$ follows from the uniqueness of $p_{s}$ and separation of the length $\theta_{s}$ of the interval $\left[0, \theta_{s}\right]$ from zero: $\theta_{s} \geqslant \Theta$, $s \in \mathbb{S}_{A}^{r}$.

It remains to prove the continuity of the mapping $s \mapsto D(s)$ defined in (2.39), (2.32). The following proposition accomplishes this objective.

Proposition 2.1.2. For each $s=\left(s_{1}, s_{2}, \ldots, s_{r+1}\right) \in \mathbb{S}_{A}^{r}$, let $\left\{\Delta_{i}(s)\right\}_{i=1}^{r}$ be defined in (2.32). Then, for $i=1, \ldots, r$,

$$
\begin{equation*}
\Delta_{i}(s) \rightarrow 0, \quad \text { as } \quad s_{i} \rightarrow 0 . \tag{2.44}
\end{equation*}
$$

Proof. By (2.30), W Whas $r$ distinct zeroes $\left\{T_{i}(s)\right\}_{i=1}^{r}$ on the interval $[0, A]$. Therefore, by the Rolle's theorem, the derivative $W_{s}^{(k)}$ has a zero on $[0, A]$ for $k=0, \ldots, r-1$. Recall that by (2.29), (2.27), $W_{s}^{(r-1)}(t)=g_{s}(t)+\alpha(s)$, $0 \leqslant t \leqslant 1$, where $\alpha(s):=q_{s}^{(r-1)}(t)$. Then, applying Proposition 1.6 and taking into account the inclusion (2.26), we infer that for $k=1, \ldots, r-1$,

$$
\begin{align*}
\left\|W_{s}\right\|_{\mathbb{C}[0, A]} & \leqslant \cdots \leqslant A^{k}\left\|W_{s}^{(k)}\right\|_{\mathbb{C}[0, A]} \leqslant \cdots \leqslant A^{r-1}\left\|W_{s}^{(r-1)}\right\|_{\mathbb{C}[0, A]} \\
& \leqslant A^{r-1}(A+\omega(A))=: C . \tag{2.45}
\end{align*}
$$

Thus, by the definition (2.32) and (2.45),
$\Delta_{i}(s)=\left\|W_{s}\right\|_{\mathrm{a}_{1}\left[\bar{i}_{i-1}(s), \bar{i}_{i}(s)\right]} \leqslant\left\|W_{s}\right\|_{\mathbb{C}[0, A]}\left|s_{i}\right| \leqslant C\left|s_{i}\right|, \quad i=1, \ldots, r$.
The estimates (2.46) imply (2.44).
Proposition 2.1.2 completes the proof of continuity of the mapping $s \mapsto \kappa(s)$.

From the definitions (2.34) of $\tilde{H}_{s}$ and (2.39) of $D(s)$ one can readily observe that the mapping $s \mapsto \kappa(s)$ is odd: $\kappa(-s)=-\kappa(s), s \in \mathbb{S}_{A}^{r}$. An application of the Borsuk's theorem (Theorem 1.4) to the mapping $\kappa$ guarantees the existence of a point satisfying the equation $\kappa(s)=0, s \in \mathbb{S}_{A}^{r}$, or equivalently,

$$
\begin{equation*}
D(s)=0, \quad a_{i}(s)=0, \quad i=1, \ldots, r, \quad s \in \mathbb{S}_{A}^{r} . \tag{2.47}
\end{equation*}
$$

Fix a solution $s^{*}$ of the equation (2.47) and put

$$
\begin{align*}
t_{i}^{*}=t_{i}\left(s^{*}\right), & \bar{t}_{i}^{*}=\bar{t}_{i}\left(s^{*}\right), & i=1, \ldots, r+1 ; \\
\tau_{i}^{*}=\tau_{i}\left(s^{*}\right), & T_{i}^{*}=T_{i}\left(s^{*}\right), & i=1, \ldots, r . \tag{2.48}
\end{align*}
$$

Lemma 2.1.3. Let $\left\{\theta_{s}\right\}_{s \in \mathbb{S}^{r}}$ be introduced in (2.36). Then,

$$
\begin{equation*}
\theta_{s^{*}}=\bar{t}_{r}^{*} \tag{2.49}
\end{equation*}
$$

Proof. Suppose, on the contrary, that $\bar{t}_{r}^{*}<\theta_{s^{*}}$. By the definition (2.35), in this case, $\theta_{s^{*}}=\Theta \leqslant 1$, and $\bar{t}_{r}^{*}:=\min \left\{t_{r}^{*}, 1\right\}=t_{r}^{*}$.

Let $s^{*}=\left(s_{1}^{*}, \ldots, s_{r+1}^{*}\right)$. From the equation $D\left(s^{*}\right)=0$ it follows that

$$
\begin{equation*}
\sum_{i=1}^{r}\left[\operatorname{sign} s_{i}^{*}\right] \Delta_{i}\left(s^{*}\right)-\frac{2 r B}{A} \sum_{i=1}^{r} s_{i}^{*}=\frac{2 r B}{A} s_{r+1}^{*} . \tag{2.50}
\end{equation*}
$$

Let us estimate the left-hand side of this equation from above and the right-hand side from below.

By (2.46) and our assumption $t_{r}^{*}=\bar{t}_{r}^{*}=\sum_{i=1}^{r}\left|s_{i}^{*}\right|<\Theta$, we have

$$
\begin{equation*}
\left|\sum_{i=1}^{r} \operatorname{sign} s_{i}^{*} \Delta_{i}\left(s^{*}\right)-\frac{2 r B}{A} \sum_{i=1}^{r} s_{i}^{*}\right| \leqslant\left(C+\frac{2 r B}{A}\right) \sum_{i=1}^{r}\left|s_{i}^{*}\right|<\left(C+\frac{2 r B}{A}\right) \Theta . \tag{2.51}
\end{equation*}
$$

On the other hand,

$$
\begin{equation*}
\left|s_{r+1}^{*}\right|=t_{r+1}^{*}-t_{r}^{*}=A-t_{r}^{*}>A-\Theta . \tag{2.52}
\end{equation*}
$$

Combining Eq. (2.50) and inequalities (2.51) and (2.52), we conclude that

$$
\left(C+\frac{2 r B}{A}\right) \Theta>\frac{2 r B}{A}(A-\Theta)
$$

or

$$
\begin{equation*}
\Theta>2 r B\left(C+\frac{4 r B}{A}\right)^{-1} \tag{2.53}
\end{equation*}
$$

This contradiction with the definition (2.35) of $\Theta$ shows that $\bar{t}_{r}^{*}>\Theta$, and

$$
\begin{equation*}
\theta_{s^{*}}=\max \left\{\Theta, \bar{t}_{r}^{*}\right\}=\bar{t}_{r}^{*} \tag{2.54}
\end{equation*}
$$

By the property (2.25), the function $H_{s^{*}}$ is not a polynomial of degree $r-1$. In particular, $\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]}>0$.

The Chebyshev theorem (Theorem 1.5) implies that the function $H_{s}(t)$ has $r+1$ points of alternance $\left\{z_{i}\right\}_{i=0}^{r}, 0 \leqslant z_{0}<z_{1}<\cdots<z_{r} \leqslant \bar{t}_{r}^{*}$, on the interval $\left[0, \bar{t}_{r}^{*}\right]=\left[0, \theta_{s^{*}}\right]$. Therefore, the derivative $(d / d t) H_{s^{*}}(t)$ has at least $r-1$ points $\left\{z_{i}\right\}_{i=1}^{r}$ of sign change on the interval [ $\left.0, \tilde{\tau}_{r}^{*}\right]$.

On the other hand, by the definition (2.38) and Eq. (2.47) for $s=s^{*}$,

$$
\begin{equation*}
\frac{d}{d t} H_{s^{*}}(t)=\frac{d}{d t} \tilde{H}_{s^{*}}(t)-\sum_{i=1}^{r-1} a_{i}\left(s^{*}\right) i t^{i-1}=U_{s^{*}}(t), \quad 0 \leqslant t \leqslant 1 . \tag{2.55}
\end{equation*}
$$

By the definition (2.33), the function $U_{s^{*}}(t)=(d / d t) H_{s^{*}}(t)$ can have at most $r-1$ points $\left\{\bar{t}_{i}^{*}\right\}_{i=1}^{r-1}$ of sign change on the interval [ $\left.0, \bar{t}_{r}^{*}\right]$. This argument shows that $(d / d t) H_{s^{*}}(t)$ has precisely $r-1$ points of sign change on [ $\left.0, \bar{i}_{r}^{*}\right]$, and

$$
\begin{equation*}
z_{i}=\bar{t}_{i}^{*}=t_{i}^{*}, \quad i=1, \ldots, r-1, \quad z_{0}=0, \quad z_{r}=\bar{t}_{r}^{*} \tag{2.56}
\end{equation*}
$$

Thus, for $\chi \in\{-1,1\}$,

$$
\begin{equation*}
H_{s^{*}}\left(\bar{t}_{i}^{*}\right)=(-1)^{i} \chi\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, \bar{i}_{r}^{*}\right]}, \quad i=0, \ldots, r . \tag{2.57}
\end{equation*}
$$

The mappings $s \mapsto \kappa(s)$ and $s \mapsto H_{s}$ are odd. Therefore, we can assume without loss of generality (if necessary, considering $-s^{*}$ ) that $\chi=(-1)^{m}$ in (2.57). By (2.57) with $\chi=(-1)^{m}$ and the definition (2.32) of $\left\{\Delta_{i}(s)\right\}_{i=1}^{r}$, we have

$$
\begin{align*}
2(-1)^{i+m}\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, \bar{i}_{r}^{*}\right]} & =H_{s^{*}}\left(\bar{t}_{i}^{*}\right)-H_{s^{*}}\left(\bar{t}_{i-1}^{*}\right) \\
& =(-1)^{i+m} \operatorname{sign} s_{i}^{*} \int_{\bar{t}_{i-1}^{*}}^{\bar{t}_{i}^{*}}\left|W_{s^{*}}(t)\right| d t \\
& =(-1)^{i+m} \operatorname{sign} s_{i}^{*} \Delta_{i}\left(s^{*}\right), \quad i=1, \ldots, r . \tag{2.58}
\end{align*}
$$

Consequently, (2.58) and (2.55) with (2.33) lead us to the conclusion that
(A) $\operatorname{sign} s_{i}^{*}=1, \quad i=1, \ldots, r$;
(B) $\quad \Delta_{i}\left(s^{*}\right)=2\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]}, \quad i=1, \ldots, r$;
(C) $\frac{d}{d t} H_{s^{*}}(t)=(-1)^{i+m}\left|W_{s^{*}}(t)\right|, \quad \bar{t}_{i-1}^{*} \leqslant t \leqslant \bar{t}_{i}^{*}, \quad i=1, \ldots, r+1$.

Our objective is to show that

$$
\begin{equation*}
\operatorname{sign} s_{r+1}^{*}=\operatorname{sign} s_{r+1}^{*}(A)=1, \tag{2.60}
\end{equation*}
$$

for all sufficiently large $A$ 's.
In order to accomplish this goal, we need to eliminate the other cases $\operatorname{sign} s_{r+1}^{*}=-1$ and $\operatorname{sign} s_{r+1}^{*}=0$.

Let us assume that $\operatorname{sign} s_{r+1}^{*}=-1$. In this case, we can compute $D\left(s^{*}\right)$ using the properties (2.59) and the definition (2.39):

$$
\begin{align*}
D\left(s^{*}\right) & =2 r\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]}-\frac{2 r B}{A} t_{r}^{*}+\frac{2 r B}{A}\left(A-t_{r}^{*}\right) \\
& =2 r\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]}-\frac{2 r B}{A}\left(2 t_{r}^{*}-A\right) . \tag{2.61}
\end{align*}
$$

Therefore, the equation $D\left(s^{*}\right)=0$ and (2.61) imply that

$$
\begin{equation*}
\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]}=\frac{B}{A}\left(2 t_{r}^{*}-A\right) . \tag{2.62}
\end{equation*}
$$

We derive two inequalities from (2.62),

$$
\begin{equation*}
t_{r}^{*}(A) \geqslant \frac{A}{2} \tag{2.63}
\end{equation*}
$$

and, using the inclusion $t_{r}^{*} \in[0, A]$,

$$
\begin{equation*}
\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]} \leqslant B \tag{2.64}
\end{equation*}
$$

If we assume that $s_{r+1}^{*}=0$, then

$$
\begin{equation*}
t_{r}^{*}:=t_{r+1}^{*}-\left|s_{r+1}^{*}\right|=t_{r+1}^{*}:=A \tag{2.65}
\end{equation*}
$$

Therefore,

$$
\begin{equation*}
D\left(s^{*}\right)=2 r\left(\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]}-\frac{B}{A} t_{r}^{*}\right)=2 r\left(\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, i_{r}^{*}\right]}-B\right)=0 . \tag{2.66}
\end{equation*}
$$

Thus,

$$
\begin{equation*}
\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, t_{r}^{*}\right]}=\left\|H_{s^{*}}\right\|_{\mathbb{C}[0,1]}=B . \tag{2.67}
\end{equation*}
$$

The pairwise combinations of properties (2.63) and (2.65), (2.64) and (2.67) lead us to the conclusion that we have two properties in the case $\operatorname{sign} s_{r+1}^{*} \leqslant 0$ :

$$
\begin{align*}
& \text { (A) }\left\|H_{s^{*}}\right\|_{\mathbb{C}[0,1]} \leqslant B \\
& \text { (B) } t_{r}^{*} \geqslant \frac{A}{2} \tag{2.68}
\end{align*}
$$

Notice that by (2.68), (B), and our choices $A>4$ and $\varepsilon<1 / r$,
(i) $\bar{t}_{r}^{*}=\min \left\{t_{r}^{*}, 1\right\}=1, \quad$ and $\quad \tau_{r}^{*}=\frac{\bar{t}_{r}^{*}+\varepsilon r}{1+\varepsilon r}=\frac{1+\varepsilon r}{1+\varepsilon r}=1$;
(ii) $\quad T_{r}^{*}=\frac{t_{r}^{*}+\varepsilon r}{1+\varepsilon r} \geqslant \frac{A / 2+\varepsilon r}{1+\varepsilon r}>\frac{A}{4}>1$.

Let us show that the inequalities (2.68), (A) and (2.68), (B) are mutually incompatible.

Indeed, by the properties (2.59), the definition (2.32) and (2.68), (A),

$$
\begin{equation*}
\left\|W_{s^{*}}\right\|_{\mathbb{L}_{1}[0,1]}=\left\|W_{s^{*}}\right\|_{\mathbb{L}_{1}\left[0, \bar{t}_{r}^{*}\right]}=\sum_{i=1}^{r} \Delta_{i}\left(s^{*}\right)=2 r\left\|H_{s^{*}}\right\|_{\mathbb{C}[0,1]} \leqslant 2 r B . \tag{2.70}
\end{equation*}
$$

By (2.27), (2.29), and (2.69), (i)

$$
\begin{equation*}
W_{s^{*}}^{(r-1)}(t)=g_{s^{*}}(t)+\alpha\left(s^{*}\right) \in H^{\omega}\left[0, \tau_{r}^{*}\right]=H^{\omega}[0,1] . \tag{2.71}
\end{equation*}
$$

Therefore, Proposition 1.8 provides two constants $\mathscr{E}_{1}=\mathscr{E}_{1}(r)$ and $\mathscr{E}_{2}=\mathscr{E}_{2}(r, \omega)$ such that

$$
\begin{equation*}
\left|W_{s^{*}}^{(r-1)}(0)\right| \leqslant \mathscr{E}_{1}\left\|W_{s^{*}}\right\|_{\mathrm{a}_{1}[0,1]}+\mathscr{E}_{2} \leqslant 2 r \mathscr{E}_{1} B+\mathscr{E}_{2} . \tag{2.72}
\end{equation*}
$$

On the other hand, by the definition (2.25) and the relations (2.69), (2.71), the function $W_{s^{*}}(t)$ is endowed with the properties
(i) $\quad(-1)^{r+m+1} W_{s^{*}}^{(r)}(t)=\frac{d}{d t} g_{s^{*}}(t)>0$, for a.e. $t \in[0, A]$;
(ii) $\quad W_{s^{*}}^{(r-1)}(t) \in H^{\omega}[0,1]$;
(iii) $W_{s^{*}}^{(r)}(t)=(-1)^{r+m+1}, \quad t \in\left[1, T_{r}^{*}\right]$;
(iv) $W_{s^{*}}$ has $r$ zeroes $\left\{T_{i}^{*}\right\}_{l=1}^{r}$ :

$$
0 \leqslant T_{1}^{*}<T_{2}^{*}<\cdots<T_{r-1}^{*} \leqslant 1<\frac{A}{4}<T_{r}^{*}
$$

Applying Proposition 1.9 to the function $(-1)^{r+m+1} W_{s^{*}}(t)$ and using the property (2.69), (ii) we obtain the following estimate for the only zero $\eta_{1}^{r-1}$ of the function $W_{s^{*}}^{(r-1)}$ :

$$
\begin{equation*}
\eta_{1}^{r-1}>\mathscr{E}_{3} T_{r}^{*}>\frac{1}{4} \mathscr{E}_{3} A>1, \quad \text { for all } \quad A \geqslant A_{0} \tag{2.74}
\end{equation*}
$$

for some constant $\mathscr{E}_{3}=\mathscr{E}_{3}(r, \omega)$ dependent only on $r, \omega$, and some $A_{0}>0$.
However, by the definition (2.24) of the function $W_{s^{*}}^{(r-1)}$,

$$
\begin{equation*}
W_{s^{*}}^{(r-1)}(t)=g_{s^{*}}(t)+\alpha\left(s^{*}\right)=(-1)^{r+m+1}\left(t-\eta_{1}^{r}\right), \quad t \in[1, A], \tag{2.75}
\end{equation*}
$$

and $W_{s^{*}}^{(r-1)}(t)$ is monotone on the whole interval $[0, A]$. Therefore, by (2.75) and the estimate (2.74),

$$
\begin{equation*}
\left|W_{s^{*}}^{(r-1)}(0)\right| \geqslant\left|W_{s^{*}}^{(r-1)}(1)\right|=\eta_{1}^{r-1}-1 \geqslant \frac{1}{4} \mathscr{E}_{3} A-1 . \tag{2.76}
\end{equation*}
$$

The juxtaposition of the estimates (2.72) and (2.76) for $\mid W_{s^{*}}(0)$ leads us to the conclusion that the inequalities become incompatible for all

$$
A>\hat{A}:=\mathscr{E}_{3}^{-1}\left(1+2 r \mathscr{E}_{1} B+\mathscr{E}_{2}\right)
$$

This contradiction shows that

$$
\begin{equation*}
\operatorname{sign} s_{r+1}^{*}(A)=1, \quad \text { for all } \quad A>\hat{A} \tag{2.77}
\end{equation*}
$$

Fix some $A>\hat{A}$. The computation of $D\left(s^{*}\right)=D\left(s^{*}, A\right)$ produces the equations

$$
\begin{equation*}
0=D_{s^{*}}=2 r\left\|H_{s^{*}}\right\|_{\mathbb{C}\left[0, \bar{i}_{r}^{*}\right]}-2 r \cdot B . \tag{2.78}
\end{equation*}
$$

Finally,

$$
\begin{equation*}
\left\|H_{s^{*}, A}\right\|_{\mathbb{C}\left[0, \bar{t}_{r}^{*}\right]}=B \tag{2.79}
\end{equation*}
$$

In order to take the limit as $\varepsilon \rightarrow 0$, we need to show that the points $\left\{\bar{t}_{i}^{*}=\bar{t}_{i}^{*}(\varepsilon)\right\}_{i=0}^{r}$ remain uniformly separated:

$$
\begin{equation*}
\left|\bar{t}_{i}^{*}(\varepsilon)-\bar{t}_{i-1}^{*}(\varepsilon)\right| \geqslant \delta, \quad i=1, \ldots, r, \quad \text { for all } \quad \varepsilon>0 \tag{2.80}
\end{equation*}
$$

Indeed, combining the estimate (2.45) with properties (2.57) and (2.79), we infer that for all $i=0, \ldots, r$,

$$
\begin{align*}
2 B & =\left|H_{s^{*}(\varepsilon)}\left(\bar{t}_{i}^{*}(\varepsilon)\right)-H_{s^{*}(\varepsilon)}\left(\bar{t}_{i-1}^{*}(\varepsilon)\right)\right| \leqslant\left\|H_{s^{*}(\varepsilon)}\right\|_{\mathbb{C}[0, A]}\left|\bar{t}_{i}^{*}(\varepsilon)-\bar{t}_{i-1}^{*}(\varepsilon)\right| \\
& =\left\|W_{s^{*}(\varepsilon)}\right\|_{\mathbb{C}[0, A]}\left|\bar{t}_{i}^{*}(\varepsilon)-\bar{t}_{i-1}^{*}(\varepsilon)\right| \leqslant C\left|\bar{t}_{i}^{*}(\varepsilon)-\bar{t}_{i-1}^{*}(\varepsilon)\right| . \tag{2.81}
\end{align*}
$$

Thus, we can put $\delta=2 B / C$ in (2.80).

The inequalities (2.45) for the norms $\left\{\left\|W_{s^{*}}^{(k)}\right\|_{\mathbb{C}[0, A]}\right\}_{k=0}^{r-1}$ and an application of the Arzela-Ascoli theorem enable us to choose a subsequence $\left\{\varepsilon_{k}\right\}_{k \in \mathbb{N}}$, $\varepsilon_{k} \downarrow 0$, as $k \uparrow \infty$, such that

$$
\begin{array}{cl}
\lim _{k \rightarrow \infty} t_{i}^{*}\left(\varepsilon_{k}\right)=t_{i}, & i=0, \ldots, r ;  \tag{2.82}\\
\lim _{k \rightarrow \infty} W_{s^{*}\left(\varepsilon_{k}\right)}(t)=W(t) & \text { in } \mathbb{C}^{r}[0,1] .
\end{array}
$$

Then, by the inequalities (2.18),

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \tau_{i}\left(\varepsilon_{k}\right)=\bar{t}_{i}:=\min \left\{t_{i}, 1\right\}, \quad \lim _{k \rightarrow \infty} T_{i}\left(\varepsilon_{k}\right)=t_{i}, \quad i=0, \ldots, r . \tag{2.83}
\end{equation*}
$$

Also, by our observation (2.56), $T_{i}=\bar{t}_{i}=t_{i}, i=0, \ldots, r-1$. Put

$$
\begin{array}{ll}
U(t)=(-1)^{i+m}|W(t)|, & \bar{t}_{i-1} \leqslant t \leqslant \bar{t}_{i}, \quad 1 \leqslant i \leqslant r+1 ; \\
H(t)=\int_{0}^{t} U(y) d y, & 0 \leqslant t \leqslant 1, \tag{2.84}
\end{array}
$$

so $U=\lim _{k \rightarrow \infty} U_{s^{*}\left(\varepsilon_{k}\right)}$ in $\mathbb{Z}_{1}[0,1]$, and $H=\lim _{k \rightarrow \infty} H_{s^{*}\left(\varepsilon_{k}\right)}$ in $\mathbb{C}[0,1]$. The comparison of the properties (2.59), (C) and (2.31) combined with the limiting relations (2.83) leads us to the conclusion that for $t \in\left[\bar{t}_{i-1}, \bar{i}_{i}\right]$, $i=1, \ldots, r+1$,

$$
\begin{equation*}
\frac{d}{d t} H(t)=U(t)=(-1)^{i+m}|W(t)|=(-1)^{i+m}\left[(-1)^{i+m} W(t)\right]=W(t) \tag{2.85}
\end{equation*}
$$

Therefore, $H \in W^{r} H^{\omega}\left[0, \bar{t}_{r}\right]$, and

$$
\begin{equation*}
H^{(k)}(t)=W^{(k-1)}(t), \quad t \in[0,1], \quad k=1, \ldots, r . \tag{2.86}
\end{equation*}
$$

By (2.80), the points $\left\{\bar{t}_{i}\right\}_{i=0}^{r}$ are separated by the constant $\delta$. Let the coefficients $\left\{\alpha_{i}\right\}_{i=0}^{r}$ be determined from the system of linear equations

$$
\begin{equation*}
\sum_{i=0}^{r} \alpha_{i}\left[\bar{t}_{i}\right]^{k}=(-1)^{m} \delta_{m, k}, \quad k=0, \ldots, r, \tag{2.87}
\end{equation*}
$$

and the kernel $K$ be introduced by the formula

$$
\begin{equation*}
K(t)=-\frac{1}{(r-1)!} \sum_{i=0}^{r} \alpha_{i}\left(\bar{t}_{i}-t\right)_{+}^{r-1} . \tag{2.88}
\end{equation*}
$$

It also follows from the property (2.80) and the definition (2.20) that

$$
\begin{equation*}
\lim _{k \rightarrow \infty} K_{s^{*}\left(\varepsilon_{k}\right)}(t)=K(t) \quad \text { in } \quad \mathbb{C}[0,1] . \tag{2.89}
\end{equation*}
$$

Therefore, we can apply Lemma 1.3 to the family of functions

$$
f_{s^{*}}(t)=W_{s^{*}\left(\varepsilon_{k}\right)}(t)-W_{s^{*}\left(\varepsilon_{k}\right)}(0), \quad 0 \leqslant t \leqslant \tau_{r}^{*}\left(\varepsilon_{k}\right), \quad k \in \mathbb{N},
$$

extremal in problems (2.21). Lemma 1.3 implies that

$$
\begin{equation*}
\sup _{h \in H_{0}^{o}\left[0, \bar{i}_{r}\right]} \int_{0}^{\bar{t}_{r}} h(t) K(t) d t=\int_{0}^{\bar{t}_{r}}\left[H^{(r)}-H^{(r)}(0)\right] K(t) d t \tag{2.90}
\end{equation*}
$$

From the properties (2.57) with $\chi=(-1)^{m}$ and (2.79) of the functions $H_{s^{*}(\varepsilon)}$ we infer that

$$
\begin{equation*}
H\left(\bar{t}_{i}\right)=(-1)^{i+m}\left\|H\left(\bar{t}_{i}\right)\right\|_{\mathbb{C}\left[0, \bar{i}_{r}\right]}=(-1)^{i+m} B . \tag{2.91}
\end{equation*}
$$

The point $t_{r}$ becomes the $r$ th zero of the derivative $(d / d t) H(t)=W(t)$ on the interval $[0,1)$, if $\bar{t}_{r}=t_{r}$, i.e., $t_{r}<1$.

It remains to rename the extremal functions and the points:

$$
\begin{equation*}
\tau_{i}:=\bar{t}_{i}, \quad i=0, \ldots, r ; \quad Z_{B}(t):=H(t), \quad K_{B}(t)=K(t), \quad t \in\left[0, \bar{t}_{r}\right] . \tag{2.92}
\end{equation*}
$$

The extension of the function $Z_{B}^{(r)}(t)$ to the entire interval [ 0,1 ] can be given by the formula

$$
\begin{equation*}
Z_{B}^{(r)}(t)=Z_{B}^{(r)}\left(\tau_{r}\right)+(-1)^{r+m+1}\left[\omega(t)-\omega\left(\tau_{r}\right)\right], \quad t \in\left[\tau_{r}, 1\right] . \tag{2.93}
\end{equation*}
$$

By Corollary 1.2 and (2.93), the function $Z_{B}^{(r)}$ has the full modulus of continuity on [0,1]:

$$
\omega\left(Z_{B}^{(r)} ; t\right)=\omega(t)=\left\{\begin{array}{l}
\omega\left(Z_{B}^{(r)} ; t\right), \quad 0 \leqslant t \leqslant \tau_{r} ;  \tag{2.94}\\
\left|Z^{(r)}(t)-Z^{(r)}(0)\right|
\end{array}\right.
$$

The derivatives $\left\{Z_{B}^{(k)}(t)\right\}_{k=0}^{r-1}$ are extended to [0,1] by continuity.
The proof of Theorem 2.1 is completed.
In conclusion, we remark that from the definition of the kernel $K(t)$ in (2.1), (2.2) for $\left\{\tau_{i}=\tau_{i}(B)^{\}}{ }_{i=0}\right.$ it follows that the kernel $K(t)=K_{m}(t)$ depends on $m, 0<m \leqslant r$. Then, the Korneichuk formula (2.6) $(0<m \leqslant r)$ and (2.11) for the $r$ th derivative $Z_{B}^{(r)}(t)$ imply that the family of Zolotarev $\omega$-polynomials $\left\{Z_{B}=Z_{B, r, m, \omega}\right\}_{B>0}$ is dependent on $m$ in the case of nonlinear modulii of continuity $\omega$.

## 3. COROLLARIES OF THEOREM 2.1

Fix $r, m \in \mathbb{N}: 0<m \leqslant r$.
Throughout this section, $\left\{\tau_{i}(B)\right\}_{i=0}^{r}$ is the set of alternance points of the function $Z_{B}=Z_{B, \omega, r, m}$ on the interval $\left[0, \tau_{r}(B)\right]$, and the kernel $K_{B}(x)$, $0 \leqslant x \leqslant 1$, is defined by (2.1), (2.2) for the specified collection $\left\{\tau_{i}=\tau_{i}(B)\right\}_{i=0}^{r}$.

### 3.1. The Uniqueness Property of Zolotarev $\omega$-Polynomials

In the following corollary we prove the uniqueness of the solution of the problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\omega}[0,1], \quad\|f\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]} \leqslant B \tag{3.1}
\end{equation*}
$$

Corollary 3.1. Let $B>0$. The function $Z_{B}$ is a unique solution of the problem (3.1).

Proof. By Theorem 2.1, $Z_{B}$ is a solution of the problem (3.1). From the identities (2.4) for $0<m<r$ and (2.9) for $m=r$ we deduce the following necessary and sufficient conditions for a function $\hat{f}$ to be extremal in the problem (3.1):
(i) $\hat{f}\left(\tau_{j}(B)\right)=(-1)^{m+j} B, \quad j=0, \ldots, r$;
(ii) $\sup _{h \in H_{0}^{o j}} \int_{0}^{\tau_{r}(B)} h(x) K_{B}(x) d x=\int_{0}^{\tau_{r}(B)}\left[\hat{f}^{(r)}(x)-\hat{f}^{(r)}(0)\right] K_{B}(x) d x$,

By the Korneichuk lemma, the extremal function in (3.2), (ii) is unique:

$$
\begin{equation*}
\hat{f}^{(r)}(x)-\hat{f}^{(r)}(0)=Z_{B}^{(r)}(x)-Z_{B}^{(r)}(0), \quad 0 \leqslant x \leqslant \tau_{r}(B) \tag{3.3}
\end{equation*}
$$

Therefore,

$$
\begin{equation*}
\hat{f}(x)=Z_{B}(x)+\sum_{i=0}^{r} c_{i} x^{i}, \quad 0 \leqslant x \leqslant \tau_{r}(B), \quad c_{i} \in \mathbb{R}, \quad i=0, \ldots, r . \tag{3.4}
\end{equation*}
$$

However, by (3.2), (i), the difference $\hat{f}(x)-Z_{B}(x)$ vanishes at $r+1$ distinct points $\left\{\tau_{i}(B)\right\}_{i=0}^{r}$. Consequently, the coefficients of the polynomial $\sum_{i=0}^{r} c_{i} x^{i}$ $=\hat{f}(x)-Z_{B}(x)$ are zeroes.
3.2. Zolotarev $\omega$-Polynomials with $r$ Alternance Points on $[0,1]$

Let us introduce the class

$$
\begin{equation*}
W^{r} H^{\omega}[B]:=\left\{f \in W^{r} H^{\omega}[0,1] \mid\|f\|_{\mathbb{C}[0,1]} \leqslant B\right\} . \tag{3.5}
\end{equation*}
$$

In the following corollary we show that $\tau_{r}(B)=1$ for all sufficiently large $B$ 's.

Corollary 3.2. Let the class $W^{r} H^{\omega}[B]$ be defined in (3.5). There exists such a constant $M=M_{\omega, r, m}>0$ that $\tau_{r}(B)=1$ for all $B>M$, and

$$
\begin{equation*}
\sup _{f \in W^{H^{\omega}} H^{\omega}[B]} f^{(m)}(0)=Z_{B}^{(m)}(0), \quad \text { for all } \quad B>M \tag{3.6}
\end{equation*}
$$

Proof. Let us introduce the set $\Gamma=\Gamma(B, r, m, \omega) \in \mathbb{R}_{+}$:

$$
\begin{equation*}
\Gamma:=\left\{B>0 \left\lvert\, \frac{d}{d t} Z_{B}\left(\tau_{r}(B)\right)=0\right.\right\} . \tag{3.7}
\end{equation*}
$$

By the assertion (iii) of Theorem 2.1, if $\tau_{r}(B)<1$, then $(d / d t) Z_{B}\left(\tau_{r}(B)\right)=0$, and $B \in \Gamma$. Therefore,

$$
\begin{equation*}
B \notin \Gamma \Leftrightarrow \tau_{r}(B)=1 \quad \text { and } \quad \frac{d}{d t} Z_{B}\left(\tau_{r}(B)\right) \neq 0 \tag{3.8}
\end{equation*}
$$

Lemma 3.2.1. Let the set $\Gamma$ be introduced by (3.7). Then,

$$
\begin{equation*}
\text { (A) } \inf _{B \in \mathbb{R}_{+} \backslash \Gamma} B>0 ; \quad \text { (B) } \sup _{B \in \Gamma} B<+\infty \text {. } \tag{3.9}
\end{equation*}
$$

Proof. Let us show that $\Gamma$ is nonempty. Indeed, otherwise, $\tau_{r}(B)=1$ for all $B>0$. Then, by Corollary 1.2.1, all functions $Z_{B}^{(r)}$ have the full modulus of continuity on $\left[0, \tau_{r}(B)\right]=[0,1]: \omega\left(Z_{B}^{(r)} ; t\right)=\omega(t), 0 \leqslant t \leqslant 1$, and

$$
(-1)^{r+m+1}\left[Z_{B}^{(r)}(1)-Z_{B}^{(r)}(0)\right]=\omega(1), \quad \text { for all } \quad B>0 .
$$

The Arzela-Ascoli theorem enables us to choose such a sequence $B_{k} \downarrow 0$, as $k \uparrow \infty$, that $\lim _{k \rightarrow \infty} Z_{B_{k}}=Z$ in $\mathbb{C}[0,1]$. Then, the contradicting properties $\|Z\|_{\mathbb{C}[0,1]}=0$ and $\left|Z^{(r)}(1)-Z^{(r)}(0)\right|=\omega(1)$ of the limiting function $Z$ prove that our assumption was wrong. Thus, the set $\Gamma$ is nonempty and $\sup _{B \in \Gamma} B>0$.

On the other hand, if $B \in \Gamma$, then the derivative $(d / d t) Z_{B}(t)$ has $r$ distinct zeroes $\left\{\tau_{i}(B)\right\}_{i=1}^{r}$ on $\left[0, \tau_{r}(B)\right]$. Thus, $Z_{B}^{(r)}$ has a zero on $\left[0, \tau_{r}(B)\right]$, and by Proposition 1.6,

$$
\begin{equation*}
B=\left\|Z_{B}\right\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]} \leqslant\left[\tau_{r}(B)\right]^{r}\left\|Z_{B}^{(r)}\right\|_{\mathbb{C}\left[0, \tau_{r}(B)\right]} \leqslant \omega(1) . \tag{3.10}
\end{equation*}
$$

Let us define the constant $M=M(\omega, r, m)$ :

$$
\begin{equation*}
M:=\sup _{B \in \Gamma}\left\|Z_{B}\right\|_{\mathbb{C}[0,1]} . \tag{3.11}
\end{equation*}
$$

$\operatorname{By}(3.8), \tau_{r}(B)=1, B \in \mathbb{R}_{+} \backslash \Gamma$. In particular, $\tau_{r}(B)=1$ for all $B>M$. Therefore,

$$
\begin{equation*}
Z_{B}\left(\tau_{i}(B)\right)=(-1)^{i+m}\left\|Z_{B}\right\|_{\mathbb{C}[0,1]}=(-1)^{i+m} B, \quad \text { for all } \quad B>M, \tag{3.12}
\end{equation*}
$$

implying the extremal property (3.6) of the function $Z_{B}$ for $B>M$.

We remark that by (3.8), functions $Z_{B}$ have the extremal property (3.6) for all $B \in \mathbb{R}_{+} \backslash \Gamma$.

The following result follows immediately from Corollaries 3.1 and 3.2 on the uniqueness of the solution of the problem

$$
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\omega}[B],
$$

for all $B \geqslant M$.

Corollary 3.2.2. Let $\left\{\tau_{i}(B)\right\}_{i=0}^{r}$ be the alternance points of the extremal functions $Z_{B}$. Then, the mapping $B \mapsto\left\{\tau_{i}(B)\right\}_{i=0}^{r}$ is continuous on the interval $[M,+\infty)$.

Let us identify the set $\Gamma$, the constant $M$, and the function $Z_{M}$ in the case of a linear modulus of continuity $\omega(t)=t$. Let $C_{r}(x)$ be the Chebyshev polynomial of degree $r+1$ defined in (0.2),

$$
L_{r}:=\left\|C_{r}\right\|_{\mathbb{C}[0,1]}=\frac{2^{-2 r-1}}{(r+1)!},\left\{T_{i}=\frac{1}{2}\left(1+\cos \frac{\pi i}{r+1}\right)\right\}_{i=0}^{r+1}
$$

be the collection of alternance points of $C_{r}(x)$ on the interval [ 0,1 ], and $K_{r}:=L_{r} \cdot T_{r}^{-(r+1)}$. Then, $\Gamma=\left(0, K_{r}\right], M=K_{r}$, and for $B \in \Gamma$, the polynomial $Z_{B}$ is given by the formula (0.4). The following section describes a similar phenomenon in Hölder classes.

### 3.3. Zolotarev $\omega$-Polynomials in Hölder Classes

Fix $\alpha, 0<\alpha \leqslant 1$, and consider the Hölder classes $W^{r} H^{\alpha}[0,1]:=$ $W^{r} H^{\omega_{\alpha}}[0,1]$, where $\omega_{\alpha}(t)=t^{\alpha}$.

The extremal functions $\left\{Z_{B}=Z_{B, r, m, \omega_{\alpha}}\right\}_{B>0}$ have the following specific feature. For a fixed $B>0$, let $\tau_{i}=\tau_{i}(B), i=0, \ldots, r$, and

$$
\begin{equation*}
\mathscr{Z}(t)=Z_{B}(t), \quad K(t)=K_{B}(t), \quad 0 \leqslant \tau_{r}(B) . \tag{3.13}
\end{equation*}
$$

For all $\beta>0$, put $B[\beta]:=\beta^{r+\alpha} B, \tau_{i}[\beta]=\beta \tau_{i}, i=0, \ldots, r$, and

$$
\begin{equation*}
Y_{\beta}(t)=\beta^{r+\alpha} \mathscr{Z}(t / \beta), \quad V_{\beta}(t)=\beta^{r-1-m} K(t / \beta), \quad 0 \leqslant t \leqslant \tau_{r}[\beta] . \tag{3.14}
\end{equation*}
$$

By the definitions (2.1), (2.2) of the kernel $K(t)$ and (3.14) of the kernel $V_{\beta}(t)$,

$$
\begin{equation*}
V_{\beta}(t)=\sum_{i=0}^{r} \alpha_{i}[\beta]\left(\tau_{i}[\beta]-t\right)_{+}^{r-1}, \tag{3.15}
\end{equation*}
$$

and the coefficients $\left\{\alpha_{i}[\beta]=\beta^{-m} \alpha_{i}\right\}_{i=0}^{r}$ satisfy the equations

$$
\begin{equation*}
\sum_{i=0}^{r} \alpha_{i}[\beta]\left(\tau_{i}[\beta]\right)^{j}=\delta_{m, j}, \quad j=0, \ldots, r . \tag{3.16}
\end{equation*}
$$

Therefore, for any function $f \in W^{r} H^{\alpha}\left[0, \tau_{r}[\beta]\right]$, the familiar identity holds:

$$
\begin{equation*}
f^{(m)}(0)=\sum_{i=0}^{r} \alpha_{i} f\left(\tau_{i}[\beta]\right)+\int_{0}^{\tau_{r}[\beta]} f^{(r)}(t) V_{\beta}(t) d t . \tag{3.17}
\end{equation*}
$$

By Corollary 1.2 .2 , applied to the dylation $V_{\beta}$ of the kernel $K$, and the assertion (i) of Theorem 2.1,

$$
\begin{equation*}
\sup _{h \in H_{0}^{\omega}\left[0, \tau_{r}[\beta]\right]} \int_{0}^{\tau_{r}[\beta]} h(t) V_{\beta}(t) d t=\int_{0}^{\tau_{r}[\beta]}\left(Y_{\beta}(t)-Y_{\beta}(0)\right) V_{\beta}(t) d t . \tag{3.18}
\end{equation*}
$$

By the assertion (ii) of Theorem 2.1 and the definition (3.14) of the function $Y_{\beta}$,

$$
\begin{equation*}
Y_{\beta}\left(\tau_{i}[\beta]\right)=(-1)^{i+m}\left\|Y_{\beta}\right\|_{\mathbb{C}\left[0, \tau_{r}[\beta]\right]}=(-1)^{i+m} B[\beta], \quad i=0, \ldots, r . \tag{3.19}
\end{equation*}
$$

The properties (3.18) and (3.19) along with the identity (3.17) imply that the function $Y_{\beta}(t)$ has the extremal property

$$
\begin{equation*}
Y_{\beta}^{(m)}(0)=\sup \left\{f^{(m)}(0) \mid f \in W^{r} H^{\alpha}\left[0, \tau_{r}[\beta]\right],\|f\|_{\mathbb{C}\left[0, \tau_{r}[\beta]\right]} \leqslant B[\beta]\right\} . \tag{3.20}
\end{equation*}
$$

This property will be used in the proof of the following results.
Lemma 3.3. Let the set $\Gamma=\Gamma\left(r, m, \omega_{\alpha}\right)$ be introduced in (3.7) and $M=M_{r, m, \omega_{\alpha}}$ be the constant defined in (3.11) for $\omega(t)=\omega_{\alpha}(t)$. Let $\left\{\tau_{i}(B)=\right.$ $\left.\tau_{i}(B, r, m, \alpha)\right\}_{i=0}^{r}$ be the points of alternance of the function $Z_{B}=Z_{B, r, m, \omega_{\alpha}}$. Then,

$$
M \in \Gamma \quad \text { and } \quad \tau_{r}(M)=1
$$

Proof. For each $B \in \Gamma$, let us introduce the function $X_{B}(t)$ and the kernel $W_{B}(t)$ :

$$
\begin{array}{rll}
X_{B}(t) & =\left[\tau_{r}(B)\right]^{-r-\alpha} Z_{B}\left(\tau_{r}(B) t\right), & 0 \leqslant t \leqslant 1 ; \\
W_{B}(t) & =\left[\tau_{r}(B)\right]^{m+1-r} K_{B}\left(\tau_{r}(B) t\right), & 0 \leqslant t \leqslant 1 \tag{3.21}
\end{array}
$$

Note that

$$
\begin{equation*}
\frac{d}{d t} X_{B}(1)=\left[\tau_{r}(B)\right]^{1-r-\alpha} \frac{d}{d t} Z_{B}\left(\tau_{r}(B)\right)=0, \quad \text { for all } \quad B \in \Gamma . \tag{3.22}
\end{equation*}
$$

Let $A_{B}=\left\|X_{B}\right\|_{\mathbb{C}[0,1]}=\left[\tau_{r}(B)\right]^{-r-\alpha} B$. As we explained in (3.18)-(3.20), the function $X_{B}$ is extremal in the problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\alpha}\left[A_{B}\right] . \tag{3.23}
\end{equation*}
$$

First, let us show that the inclusion $M \in \Gamma$ implies the property $\tau_{r}(M)=1$. Indeed, if $\tau_{r}(M)<1$, then $A_{M}>M$ and, consequently, $A_{M} \notin \Gamma$. Therefore, by Corollaries 3.1 and $3.2, \tau_{r}\left(A_{M}\right)=1$ and the function $Z_{A_{M}}$ is a unique solution of the problem (3.23) for $B=M$. Thus, $X_{M}=Z_{A_{M}}$. Then, by the property (3.22), $(d / d t) Z_{A_{M}}(1)=(d / d t) X_{M}(1)=0$, and the definition (3.7) of the set $\Gamma$ implies $A_{M} \in \Gamma$. Then, the contradicting inclusions $A_{M} \in \Gamma$ and $A_{M} \notin \Gamma$ prove that $\tau_{r}(M)=1$.

It remains to eliminate the case $M \notin \Gamma$. In this case, let us consider such a subsequence $\left\{B_{i}\right\}_{i \in \mathbb{N}}$ that $B_{i} \in \Gamma, i \in \mathbb{N}, \lim _{i \rightarrow \infty} B_{i}=M$, and

$$
\begin{align*}
& \lim _{i \rightarrow \infty}\left(\tau_{0}\left(B_{i}\right), \ldots, \tau_{r}\left(B_{i}\right)\right)=\left(T_{0}, \ldots, T_{r}\right) ; \\
& \lim _{i \rightarrow \infty} X_{B_{i}}=\mathscr{X}(t) \quad \text { in } \mathbb{C}^{r}[0,1] ;  \tag{3.24}\\
& \lim _{i \rightarrow \infty} W_{B_{i}}(t)=W(t)=\sum_{i=0}^{r} \alpha_{i}\left(T_{i}-t\right)_{+}^{r-1} \quad \text { in } \quad \mathbb{C}^{r-1}[0,1],
\end{align*}
$$

where the coefficients $\left\{\alpha_{i}\right\}_{i=0}^{r}$ satisfy Eq. (2.1) for $\left\{\tau_{i}=T_{i}\right\}_{i=0}^{r}$.
Let $D=M T_{r}^{-r-\alpha}$. By Lemma 1.3, applied to the family of kernels $\left\{W_{B_{i}}\right\}_{i \in \mathbb{N}}$, the function $\mathscr{X}(t)$ inherits the properties of functions $\left\{X_{B_{i}}\right\}_{i \in \mathbb{N}}$ :

$$
\begin{equation*}
\mathscr{X}\left(T_{i}\right)=(-1)^{i+m}\|\mathscr{X}\|_{\mathbb{C}[0,1]}=(-1)^{i+m} D, \quad i=0, \ldots, r \tag{i}
\end{equation*}
$$

(ii) $\sup _{h \in H_{0}^{\sigma}[0,1]} \int_{0}^{1} h(t) W(t) d t=\int_{0}^{1}\left[X^{(r)}(t)-X^{(r)}(0)\right] W(t) d t$;
(iii) $\frac{d}{d t} \mathscr{X}(1)=0$.

Therefore, the function $\mathscr{X}(t)$ is extremal in the problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\alpha}[D] \tag{3.26}
\end{equation*}
$$

Since $D \geqslant M$, our assumption $M \notin \Gamma$ implies that $D \notin \Gamma$, as well. Therefore, by Corollary 3.2, the function $Z_{D}$ is a unique solution of the problem
(3.26). Thus, $X(t)=Z_{D}(t)$. Then, the property (3.25), (iii) implies that $D \in \Gamma$. Once again, the contradicting inclusions $D \in \Gamma$ and $D \notin \Gamma$ lead us to the conclusion that our assumption $M \notin \Gamma$ was wrong.

### 3.4. Chebyshev $\omega$-Polynomials in $W^{r} H^{\alpha}[0,1]$

In the following corollary we construct the analog $C(x)=C_{r, m, \alpha}(x)$ of the Chebyshev polynomial in the Hölder space $W^{r} H^{\alpha}[0,1]$. Like in the linear case $\omega(t)=A t$, we describe all extremal functions in the problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\omega}[B] \tag{3.27}
\end{equation*}
$$

for $B \geqslant L$.

Corollary 3.4. Let $0<\alpha \leqslant 1$.

1. There exist a constant $L=L_{\alpha, r, m}>0$, the collection of points $\left\{T_{i}=T_{i}(r, m, \alpha)\right\}_{i=0}^{r+1}: 0=T_{0}<T_{1}<\cdots<T_{r}<T_{r+1}=1$, and the function $C(x)=C_{\alpha, r, m}(x)$ endowed with the properties

$$
\begin{align*}
& \text { (i) } \quad C\left(T_{i}\right)=(-1)^{i+m}\|C\|_{\mathbb{C}[0,1]}=(-1)^{i+m} L \quad i=0, \ldots, r+1 ;  \tag{i}\\
& \text { (ii) } \sup _{h \in H_{0}^{x}\left[0, T_{r}\right]} \int_{0}^{T_{r}} h^{(r)}(t) \mathscr{K}(t) d t=\int_{0}^{T_{r}}\left[C^{(r)}(t)-C^{(r)}(0)\right] \mathscr{K}(t) d t, \tag{3.28}
\end{align*}
$$

where $\mathscr{K}(t)$ is defined by (2.1), (2.2) for $\left\{\tau_{i}=T_{i}\right\}_{i=0}^{r}$;
(iii) $\quad \omega\left(C^{(r)} ; t\right)=\omega_{\alpha}(t), \quad 0 \leqslant t \leqslant 1$.
2. For any $B \geqslant L$ there exists a collection of points $\left\{\tau_{i}=\tau_{i}(r, m, \alpha, B)\right\}_{i=0}^{r}$ : $0=\tau_{0}<\tau_{1}<\cdots<\tau_{r} \leqslant 1$, and a function $Z_{B}(t) \in W^{r} H^{\omega}[0,1]$ with the properties

$$
\begin{equation*}
Z_{B}\left(\tau_{i}\right)=(-1)^{i+m}\left\|Z_{B}\right\|_{\mathbb{C}[0,1]}=(-1)^{i+m} B, \quad i=0, \ldots, r ; \tag{i}
\end{equation*}
$$

(ii) $\sup _{h \in H_{0}^{\alpha}\left[0, \tau_{r}\right]} \int_{0}^{\tau_{r}} h^{(r)}(t) K_{B}(t) d t=\int_{0}^{\tau_{r}}\left[Z_{B}^{(r)}(t)-Z_{B}^{(r)}(0)\right] K_{B}(t) d t$,
where $K_{B}(t)$ is defined by (2.1), (2.2);
(iii) $\quad \omega\left(Z_{B}^{(r)} ; t\right)=\omega_{\alpha}(t), \quad 0 \leqslant t \leqslant 1$.
3. For any $B \geqslant L$, the function $Z_{B}(x)=Z_{\alpha, r, m, B}(x)$ is extremal in (3.27).

Proof. Let $M=M\left(r, m, \omega_{\alpha}\right)$ be the constant defined in (3.11) for $\omega=\omega_{\alpha}$. By Lemma 3.3, $\tau_{r}(M)=1$, so the function $Z_{M}$ is defined on the whole interval [ 0,1 ]. Let

$$
\mathscr{Z}^{(r)}(t)= \begin{cases}\boldsymbol{Z}_{M}^{(r)}(t), & 0 \leqslant t \leqslant 1 ;  \tag{3.30}\\ \boldsymbol{Z}_{M}^{(r)}(0)+(-1)^{r+m+1} \omega(t), & t>1 .\end{cases}
$$

Then, the extension $\mathscr{Z}(t)$ of the function $Z_{M}(t)$ from the interval [ 0,1$]$ to the entire half-line $\mathbb{R}_{+}$is given by the formula

$$
\begin{equation*}
\mathscr{Z}(t)=\sum_{i=0}^{r-1} \frac{Z_{M}^{(i)}(0)}{i!} t^{i}+\frac{1}{r!} \int_{0}^{t} \mathscr{Z}^{(r)}(x)(t-x)_{+}^{r-1} d x, \quad t \in \mathbb{R}_{+} . \tag{3.31}
\end{equation*}
$$

Let us show that $\mathscr{Z} \in W^{r} H^{\alpha}\left(\mathbb{R}_{+}\right)$. By the definition, we have the inclusions $\left.\mathscr{Z}^{(r)}\right|_{[0,1]} \in H^{\alpha}[0,1]$ and $\left.\mathscr{Z}^{(r)}\right|_{[1,+\infty)} \in H^{\alpha}[1,+\infty)$. It remains to verify the inequality

$$
\begin{equation*}
\left|\mathscr{Z}^{(r)}\left(t_{2}\right)-\mathscr{Z}^{(r)}\left(t_{1}\right)\right| \leqslant \omega_{\alpha}\left(t_{2}-t_{1}\right), \quad \text { for } \quad t_{1} \in[0,1], \quad t_{2}>1 \tag{3.32}
\end{equation*}
$$

In this case, the definition (3.30) of $\mathscr{Z}^{(r)}$ and the concavity of $\omega_{\alpha}(t)$ lead us to the following chain of inequalities:

$$
\begin{align*}
\left|\mathscr{Z}^{(r)}\left(t_{2}\right)-\mathscr{Z}^{(r)}\left(t_{1}\right)\right|= & \left|\mathscr{Z}^{(r)}\left(t_{2}\right)-\mathscr{Z}^{(r)}(1)\right|+\left|\mathscr{Z}^{(r)}(1)-\mathscr{Z}^{(r)}\left(t_{1}\right)\right| \\
\leqslant & {\left[\omega_{\alpha}\left(t_{2}\right)-\omega_{\alpha}(1)\right]+\omega_{\alpha}\left(1-t_{1}\right) } \\
\leqslant & {\left[\omega_{\alpha}\left(t_{2}-t_{1}\right)-\omega_{\alpha}\left(1-t_{1}\right)\right] } \\
& +\omega_{\alpha}\left(1-t_{1}\right)=\omega_{\alpha}\left(t_{2}-t_{1}\right) \tag{3.33}
\end{align*}
$$

Moreover, by the definition (3.30) and Corollary 1.2.1 of the Korneichuk lemma, the function $\mathscr{Z}^{(r)}(t)$ has the full modulus of continuity on $\mathbb{R}_{+}$:

$$
\omega\left(\mathscr{Z}^{(r)} ; t\right)=\omega(t)= \begin{cases}\omega\left(Z_{M}^{(r)} ; t\right), & 0 \leqslant t \leqslant 1 ;  \tag{3.34}\\ \left|Z^{(r)}(t)-Z^{(r)}(0)\right|, & t>1 .\end{cases}
$$

For each $\beta \in[0,1]$ let us introduce the function $P_{\beta} \in W^{r} H^{\omega}\left(\mathbb{R}_{+}\right)$:

$$
\begin{equation*}
P_{\beta}(t):=\beta^{r+\alpha} \mathscr{Z}(t / \beta), \quad t \in \mathbb{R}_{+} . \tag{3.35}
\end{equation*}
$$

Put

$$
\begin{equation*}
M[\beta]:=\beta^{r+\alpha} M, \quad \tau_{i}[\beta]:=\beta \tau_{i}(M), \tag{3.36}
\end{equation*}
$$

where $M=\left\|Z_{M}\right\|_{\left.\mathbb{C}_{[0,1]}\right]}$ and $\left\{\tau_{i}(M)\right\}_{i=0}^{r}$ are the points of alternance of $Z_{M}$. The points $\left\{\tau_{i}[\beta]\right\}_{i=0}^{r}$ are the alternance points of $P_{\beta}$ on the interval $[0, \beta]$ :

$$
\begin{equation*}
P_{\beta}\left(\tau_{i}[\beta]\right)=(-1)^{i+m}\left\|P_{\beta}\right\|_{\mathbb{C}[0, \beta]}=(-1)^{i+m} M[\beta] . \tag{3.37}
\end{equation*}
$$

By our observation (3.20), the restriction $\left.P_{\beta}\right|_{[0, \beta]}$ has the extremal property

$$
\begin{equation*}
P_{\beta}^{(m)}(0)=\sup \left\{f^{(m)}(0) \mid f \in W^{r} H^{\alpha}[0, \beta],\|f\|_{\mathbb{C}[0, \beta]} \leqslant M[\beta]\right\} . \tag{3.38}
\end{equation*}
$$

Also note that by Corollary 3.3, the derivative $(d / d t) P_{\beta}(t)$ has the $r$ th zero at the point $\tau_{r}[\beta]=\beta$ :

$$
\frac{d}{d t} P_{\beta}(\beta):=\beta^{r+\alpha-1} \frac{d}{d t} Z_{M}(1)=0, \quad \text { since } \quad M \in \Gamma .
$$

From the monotonicity of $P_{\beta}^{(r)}(t)$ on $\mathbb{R}_{+}$and Rolle's theorem it follows that the derivative $(d / d t) P_{\beta}(t)$ vanishes only at $r$ points $\left\{\tau_{i}[\beta]\right\}_{i=1}^{r}$ and

$$
\begin{equation*}
\operatorname{sign} \frac{d}{d t} P_{\beta}(t)=(-1)^{i+m+1}, \quad t \in\left(\tau_{i}[\beta], \tau_{i+1}[\beta]\right), \quad i=0, \ldots, r, \tag{3.39}
\end{equation*}
$$

where $\tau_{r+1}[\beta]:=\infty$. In particular, the function $(-1)^{r+m} P_{\beta}(t)$ strictly decreases from $\left\|P_{\beta}\right\|_{\mathbb{C}[0, \beta]}$ to $-\infty$, as $t$ increases from $\tau_{r}[\beta]$ to $+\infty$.

Let us introduce the parameter $k(\beta)$ by the equation

$$
\begin{equation*}
P_{\beta}(1)=k(\beta) P_{\beta}\left(\tau_{r}[\beta]\right) . \tag{3.40}
\end{equation*}
$$

By the definition (3.35) of the function $P_{\beta}$ and the property (3.37),

$$
\begin{align*}
k(\beta) & =P_{\beta}(1)\left[P_{\beta}\left(\tau_{r}[\beta]\right)\right]^{-1} \\
& =\beta^{r+\alpha} Z_{M}(1 / \beta)\left[(-1)^{r+m} \beta^{r+\alpha} M\right]^{-1} \\
& =(-1)^{r+m} Z_{M}(1 / \beta) M^{-1} . \tag{3.41}
\end{align*}
$$

This expression for $k(\beta)$ coupled with the property (3.39) for $i=r$ implies that the function $k(\beta)$ is continuous and strictly decreases from 1 to $-\infty$, as $\beta$ decreases from 1 to 0 . In particular, there exists such a $\beta^{*} \in(0,1)$ that

$$
\begin{equation*}
k\left(\beta^{*}\right)=-1, \quad \text { and } \quad-1 \leqslant k(\beta) \leqslant 1, \quad \text { if } \quad \beta^{*} \leqslant \beta \leqslant 1 . \tag{3.42}
\end{equation*}
$$

Therefore, by (3.39) for $i=r$ and (3.42), the monotonicity of $P_{\beta}(t)$ on the interval $\left[\tau_{r}[\beta], 1\right]$ implies that for all $\beta \in\left[\beta^{*}, 1\right]$, and $t \in\left[\tau_{r}(B), 1\right]$

$$
\begin{equation*}
\left|P_{\beta}(t)\right| \leqslant \max \left\{\left|P_{\beta}\left(\tau_{r}[\beta]\right),|k(\beta)| \cdot\right| P_{\beta}\left(\tau_{r}[\beta]\right) \mid\right\}=\left\|P_{\beta}\right\|_{\mathbb{C}[0, \beta]} . \tag{3.43}
\end{equation*}
$$

Thus, we have the following refinements of the property (3.37),

$$
\begin{equation*}
P_{\beta}\left(\tau_{i}[\beta]\right)=(-1)^{i+m}\left\|P_{\beta}\right\|_{\mathbb{C}[0,1]}=(-1)^{i+m} M[\beta], \quad i=0, \ldots, r \tag{3.44}
\end{equation*}
$$

and the property (3.38),

$$
\begin{equation*}
\sup _{H^{\alpha}[M[\beta]]} f^{(m)}(0)=P_{\beta}^{(m)}(0) . \tag{3.44}
\end{equation*}
$$

Finally, by (3.37) and (3.42), $P_{\beta^{*}}(1)=k\left(\beta^{*}\right) P_{\beta}\left(\tau_{r}[\beta]\right)=(-1)^{r+m+1}$ $\left\|P_{\beta^{*}}\right\|_{c[0,1]}$, so the function $P_{\beta^{*}}(t)$ has precisely $r+2$ points of alternance $\left\{\tau_{i}\left[\beta^{*}\right]\right\}_{i=0}^{r}$ and $\tau_{r+1}\left[\beta^{*}\right]=1$. Put

$$
\begin{equation*}
C(x):=P_{\beta^{*}}(x), \quad x \in[0,1], \quad L:=\|C\|_{\mathbb{C}[0,1]} . \tag{3.45}
\end{equation*}
$$

Summarizing, the family of functions $P_{\beta}, \beta^{*} \leqslant \beta \leqslant 1$, constitutes the set of solutions of the problem (3.27) for $B \in[L, M]=\left[\|C\|_{\mathbb{C}[0,1]},\left\|Z_{M}\right\|_{\mathbb{C}[0,1]}\right]$. By Corollary 3.2, the functions $Z_{B}, B>M$, are extremal in the problem (3.27) for $B>M$.

### 3.5. Full Solution of the Kolmogorov-Landau Problem in $W^{2} H^{\omega}[0,1]$

Before characterizing extremal functions in the problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{2} H^{\omega}[B] \tag{3.46}
\end{equation*}
$$

for $m=1,2$, and all $B>0$, we make the following observation on the possibility of functional extensions from the class $W^{2} H^{\omega}[0,1]$ to the class $W^{2} H^{\omega}\left(\mathbb{R}_{+}\right)$without increasing the $\mathbb{Q}_{\infty}$-norm.

Suppose that the derivative $(d / d t) g(t)$ of a function $g \in W^{2} H^{\omega}[0,1]$ has two zeroes $t_{1}, t_{2}, 0 \leqslant t_{1}<t_{2} \leqslant 1$. Let $\Delta=t_{2}-t_{1}$. Then, the extension $E\left(g ; t_{1}, t_{2} ; \cdot\right)$ of the function $g(\cdot)$ from the interval $\left[0, t_{2}\right]$ to the entire half-line $\mathbb{R}_{+}$is given by the formula
$E\left(g ; t_{1}, t_{2} ; t\right)$

$$
= \begin{cases}g(t), & 0 \leqslant t \leqslant t_{2} ;  \tag{3.47}\\ g(t-2 n \Delta), & t_{2}+(2 n-1) \Delta \leqslant t \leqslant t_{2}+2 n \Delta, \quad n \in \mathbb{N} ; \\ g\left(2 t_{2}+2(n+1) \Delta-t\right), & t_{2}+2(n-1) \Delta \leqslant t \leqslant t_{2}+(2 n-1) \Delta .\end{cases}
$$

The properties $(d / d t) g\left(t_{1}\right)=(d / d t) g\left(t_{2}\right)=0$ assure the continuity of $(d / d t) g(t)$ on $\mathbb{R}_{+}$. In addition,

$$
\omega\left(E^{(2)}\left(g ; t_{1}, t_{2} ; \cdot\right) ; t\right)= \begin{cases}\omega(g ; t), & 0 \leqslant t \leqslant t_{2} ;  \tag{3.48}\\ \omega\left(g ; t_{2}\right), & t>t_{2} .\end{cases}
$$

Thus, $E\left(g ; t_{1}, t_{2} ; t\right) \in W^{2} H^{\omega}\left(\mathbb{R}_{+}\right)$. Also notice that

$$
\begin{equation*}
\left\|E\left(g ; t_{1}, t_{2} ; \cdot\right)\right\|_{\mathbb{L}_{\infty}\left(\mathbb{R}_{+}\right)}=\|g\|_{\mathbb{C}\left[0, t_{2}\right]} . \tag{3.49}
\end{equation*}
$$

Therefore, we extended the function $g$ to the entire half-line $\mathbb{R}_{+}$without leaving the class $W^{2} H^{\omega}\left(\mathbb{R}_{+}\right)$and increasing the $L_{\infty}$ norm.

Fix $m, m=1,2$, and $B>0$. In Theorem 2.1 for $r=2$ we proved the existence of such a function $Z_{B}$ with three points of alternance $\left\{\tau_{i}(B)\right\}_{i=0}^{2}$ that $Z_{B}$ is extremal in the problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{2} H^{\omega}[0,1], \quad\|f\|_{\mathbb{C}\left[0, \tau_{2}(B)\right]} \leqslant B \tag{3.50}
\end{equation*}
$$

Therefore, if $\tau_{2}(B)=1$, then the function $Z_{B}$ is extremal in the problem (3.46).

By the assertion (iii) of Theorem 2.1, $(d / d t) Z_{B}\left(\tau_{2}(B)\right)=0$, if $\tau_{2}(B)<1$. Besides, the derivative $(d / d t) Z_{B}(t)$ vanishes at the interior point $\tau_{1}(B)$ of extremum of $Z_{B}(t)$. Therefore, by (3.51), the restriction $E\left(Z_{B} ; \tau_{1}(B)\right.$, $\left.\tau_{2}(B) ; t\right)\left.\right|_{[0,1]}$ is extremal in problem (3.47), if $\tau_{2}(B)<1$.

Kolmogorov-Landau problems in functional classes $W^{2} H^{\omega}(\mathbb{R})$ and $W^{2} H^{\omega}\left(\mathbb{R}_{+}\right)$are solved in [4].

## 4. CONCLUDING REMARKS

The complete solution of the Kolmogorov-Landau problem

$$
f^{(m)}(0) \rightarrow \sup , \quad f \in W_{\infty}^{r+1}[0,1], \quad\|f\|_{\mathbb{C}[0,1]} \leqslant B
$$

in the Sobolev class $W_{\infty}^{r+1}[0,1]$ was given by S. Karlin [7] who constructed the family of extremal Zolotarev perfect splines $\left\{\mathscr{Z}_{B}\right\}_{B>0}$. For each $B>0$, the function $\mathscr{Z}_{B}$ of the norm $B$ has $n=n(B) \geqslant 0$ knots and oscillates $n+r+1$ times between $B=\left\|\mathscr{Z}_{B}\right\|_{\mathbb{C}[0,1]}$ and $-B$. It can be seen from the corresponding numerical differentiation formulae (see [8]) that the complete solution of the Kolmogorov-Landau problem in $W^{r} H^{\omega}[0,1]$, requires an appropriate generalization of the notion of perfect splines in functional classes $W^{r} H^{\omega}[0,1]$.

In our paper [2] we give the characterization of the structure and the description of various properties of extremal functions in the problem

$$
\begin{equation*}
\int_{a}^{b} h(t) \psi(t) d t \rightarrow \sup , \quad h \in H_{0}^{\omega}[a, b], \tag{*}
\end{equation*}
$$

for kernels $\psi \in \mathbb{R}_{1}[a, b]$ with a zero mean on $[0,1]$ and a finite or ordered countable set of points of sign change on the interval $[a, b],-\infty \leqslant a<$ $b \leqslant+\infty$. The extremal functions of the problem (*) feature as the $r$ th derivatives of solutions of the problem

$$
\begin{equation*}
f^{(m)}(0) \rightarrow \sup , \quad f \in W^{r} H^{\omega}(I), \quad\|f\|_{\mathbb{L}_{\infty}[I]} \leqslant B \tag{P.1}
\end{equation*}
$$

for $0<m<r$ and $I=[0,1], \mathbb{R}, \mathbb{R}_{+}$. The problem (P.1) for $m=r$ and $I=[0,1]$ or $I=\mathbb{R}_{+}$necessitated our solution in [3] of the problem (*) for kernels with nonzero means.

The solution and corresponding numerical differentiation formulae in the pointwise Kolmogorov-Landau problem

$$
\begin{equation*}
f^{(m)}(\xi) \rightarrow \sup , \quad f \in W_{\infty}^{r+1}[0,1], \quad\|f\|_{\mathbb{C}[0,1]} \leqslant B, \tag{P.2}
\end{equation*}
$$

were found by A. Pinkus [11]. In [3] we also describe the extremal functions of the problem

$$
\begin{equation*}
\int_{a}^{0} h(t) \psi_{1}(t) d t+\int_{0}^{b} h(t) \psi_{2}(t) d t \rightarrow \sup , \quad h \in H^{\omega}[a, b], \quad h(0)=E \in \mathbb{R}, \tag{**}
\end{equation*}
$$

for $a<0<b$, and integrable kernels $\psi_{1}$ and $\psi_{2}$ with finite or ordered countable set of points of sign change on $[a, 0]$ and $[0, b]$, respectively. As an example of an application of the extremal functions of the problem (**), we mention the version of the problem (P.2) of maximizing the $r$ th derivative of functions from $W^{r} H^{\omega}[a, b]$ at an interior point $\xi \in(a, b)$. Since extremal functions of problems $(*)$ and $(* *)$ generalize standard perfect polynomial splines; we call them the perfect $\omega$-splines.

Finally, the formulations of some results and referrences to our papers in the area of Kolmogorov-Landau inequalities in functional classes $W^{r} H^{\omega}[I]$ may be found in [3] and [4].

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